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AUTOMATIC RECOGNITION OF PRINTED MUSIC
IN THE CONTEXT OF ELECTRONIC PUBLISHING

BY

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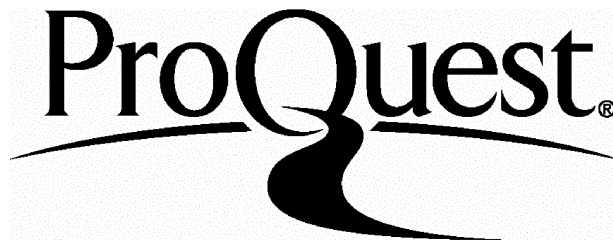
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Abstract

Computers are used to manipulate music in various forms, for example digital sound recordings, digitized images of printed scores and music representational language (M.R.L.) encodings. This work is concerned with producing M.R.L. data automatically from existing printed music scores.

A review of work undertaken in the field of manipulating printed music by computer is provided. This shows that software which permits production of high-quality scores is commercially available, but the necessary data has to be entered using some form of keyboard, possibly in conjunction with a pointing device. It is desirable, for reasons detailed in this work, to be able to convert the musical information contained in the enormous quantity of existing music into computer-readable form. The only practical method for achieving this is via an automatic system. Such an automatic system must cope with the variations in format, content and print-quality of existing scores.

Background material relating to previous work on pattern recognition of various types of binary image is included, with a section covering the subject of automatic recognition of printed music. An original system for automatic recognition of printed music developed by the author is described. This is designed to be widely applicable and hence is, in effect, omnifont and size-independent, with significant tolerance of noise, limited rotation, broken print and distortion. Numerous illustrations

showing the application of the system are included, together with proposals for future areas of development.

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This work is dedicated to my father and mother.

1. Introduction

Computers are used to manipulate music in various forms, for example digital sound recordings, digitized images of printed scores or music representational language (M.R.L.) encodings. This work is concerned with producing M.R.L. data automatically from existing printed music scores.

Computers are commonly used in the manipulation of text and graphics, whether it be creating original work or editing and analysing existing material. The distinction must be made between an image of the material and a representation of the information contained within that image. For instance, a facsimile machine transmits a bit-map image of a page without having any 'knowledge' of the meaning of the symbols or graphics on that page. In contrast, a text document produced by a word-processor is stored as an encoding of the characters used. This enables manipulation of the letters and words involved, for example by globally searching for and replacing one term with another.

Similarly, printed music can be manipulated by the computer in two forms, i.e. a bit-map ('electronic photograph') or an encoding using a music representational language. The former can be used to simply store and retrieve a digitized version of the original printed page, whilst also enabling the use of digital image processing techniques, perhaps to enhance or scale the image. An encoded version of the music printed on the original page can, however, be manipulated in various ways. Thus,

operations such as editing or automatic production of parts from a score are made possible, given the appropriate software. Further possibilities include the production of braille scores or new editions in conventional notation, musicological analysis and electronic publishing.

The above operations are, in fact, equivalent to those now performed on text. The transformation of a small proportion of the enormous amount of existing music into music representational language data by any means other than an automatic system would, however, be an impractical task. The possibility of using a computer to encode the music automatically makes the process possible, although admittedly still a large undertaking.

The text of this thesis is arranged as follows:-

Chapter 2 presents an overview of work undertaken in the field of manipulating printed music by computer. This includes an examination of the various methods available for entering into the computer the information contained in existing scores and a study of the techniques involved in storing the data. A summary of hardware available for the printing of music and a table of significant software packages for printing music are also included. The chapter is a revised and updated version of a previously published paper [Carter 1988]. The discussion of printing hardware has been revised to take account of recent developments in xerographic printers and the increase in significance of the Postscript page description language (P.D.L.). Also, the table of music printing systems has been modified to

include some new entries and increase the information pertaining to systems which have increased in importance.

Chapter 3 provides background information on the subject of pattern recognition, concentrating specifically on the processing of binary images such as engineering drawings, circuit diagrams and flowcharts. A review of past work on pattern recognition of printed music scores is included, which examines the specific problems involved in dealing with this particular class of binary image. The background is thus provided for an in-depth examination of the author's system for automatic production of M.R.L. data from existing printed music scores.

Chapter 4 contains such an analysis. The process from digitized image to M.R.L. data is broken down into its constituent parts, including filtering, staveline-finding, object (symbol) formation and recognition. Illustrations of the various stages are provided.

Chapter 5 contains worked examples of a more substantial nature showing the application of the above system, again, with appropriate illustrations. These examples form the basis of a discussion which covers various aspects of the music recognition problem in detail, including the location of the stavelines when these are substantially obscured, processing handwritten material and dealing with a multi-stave system. Suggestions for solutions to the problems which have arisen are given.

Chapter 6 summarises the qualities of the system described in

chapters 4 and 5 and describes the equipment used for the development work. Some of the possibilities for the future of the system are outlined.

2. The Acquisition, Representation and Reconstruction of Printed Music by Computer: A Review.

2.1 INTRODUCTION

The varied applications of computers to music include sound synthesis, computer-assisted composition, computer-aided instruction, music analysis and music printing. In each application there exists a dividing line between music as sound and as print. This boundary delineates the present study, which deals only with the graphical record, from aspects of sound synthesis and computer-assisted composition. For the latter, the reader is directed to frequent articles in the *Computer Music Journal* and the recent review by Yavelow [Yavelow 1987], which also includes a useful glossary of terms used in applications of computers to music. Within the subject of printed music, this review and the subsequent chapters concentrate, except where specified, on conventional Western music.

The three sections of the chapter heading - acquisition, representation and reconstruction of printed music - might well be supplemented by computerized music-setting, i.e., the design of software to implement the processes which normally fall to the music engraver. However, two major works of the literature [Gomberg 1975] [Byrd 1984] have specifically covered the topic of computerized music-setting in great detail, including fairly recent developments. This chapter therefore touches on matters connected with music-setting only where these are inextricably linked to other subjects within the province of this review.

Section 2.5 alphabetically lists a wide selection of past and present computer systems for printing music.

The large number of periodicals surveyed is due to the interdisciplinary nature of the subject. *Computers and the Humanities* and *Computer Music Journal* are the main sources, with a few references to each of numerous other periodicals, including *Journal of Music Theory*, *Perspectives of New Music* and *Fontes Artis Musicae*. Conference proceedings, other review articles and dissertations have also been consulted. A small number of books covering the subjects of music engraving, music notation and manuscript layout, which have been widely referenced elsewhere, are included in the bibliography, as they form a useful foundation for any work on computerized music printing [Donato 1963, Ross 1970, Gamble 1971, Read 1974, Read 1978, Stone 1980, Rastall 1983].

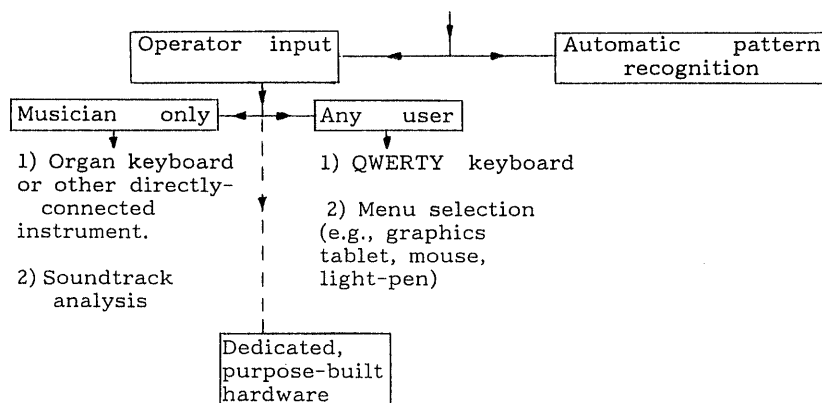
2.2 ACQUISITION

Acquisition covers the process of transferring music into the computer's music representational language. Several different methods of achieving this have been tried, and although it is difficult to divide them into rigid categories, distinctions can be made.

Automatic pattern recognition by optical scanner can be taken as a distinct category. The other methods can be separated into those accessible to anybody with a general knowledge of music notation and those usable only by a musician. For example, use of

an organ keyboard would suggest the latter category.

This paradigm can be illustrated diagrammatically :-



Whatever method is used, the aim is assumed to be an encoding which uses an internal music representational language (MRL). In real music acquisition systems various overlaps occur, such as when an organ keyboard is used in conjunction with a graphics tablet [Wittlich 1978a]. This overlap suggests an alternative categorization which involves dividing up the information encoded in a page of printed music into three basic types and associating each with an input device. Thus, pitch may be entered using an organ keyboard, rhythm could be determined by selecting from an on-screen menu of durations using a mouse, and miscellaneous symbols, like slurs, dynamics or text, could be entered using a purpose-built keyboard.

2.2.1 Automatic pattern recognition of printed music

Past and present work on pattern recognition of printed music

is described in detail in chapters 3, 4 and 5. Chapter 3 also provides a discussion of work in the general field of pattern recognition of binary images.

2.2.2 Operator input

There are two musician-only methods which attempt to capture all possible information represented in a score. One uses a directly-connected musical instrument (usually an organ keyboard) while the other involves analysing a soundtrack recording of a performance of the score.

2.2.2.1 Directly-connected instrument

It is impractical to encode all the information represented in a score by sole use of an organ or electronic piano-type keyboard (hereafter organ keyboard), and it would also appear impossible to convert into 100% accurate notation all the information present in an organ keyboard performance [Knowlton 1971, 1972]. A major problem discussed by Raskin [1980a, 1980b] and Clements [1980a] is rhythm-fitting, since no performance contains, throughout, durations which are fully consistent with the notation. Voice assignment has been found to be an intractable problem [Maxwell 1983, 1984] [Byrd 1984]. For example, if two voices out of three in a three-voiced composition are sounding in unison, it is impossible for the system to know whether two or three voices are actually sounding.

Enharmonic notation is another problem of some magnitude. In

tonal music, guidelines might be formulated to assist the machine in determining which particular notation is meant, but for atonal music the problem appears insurmountable [Byrd 1984] [Gomberg 1975, 1977].

Thus, provided the user circumvents the limitations of using an organ keyboard as an input device, it can still form part of a practical system.

2.2.2.2 Soundtrack analysis

Early work in this field by Moorer [1975, 1977] limited input to no more than two voices with further restrictions on the harmonic relationship between simultaneously sounding notes. He stated that 'In general, the system works tolerably well on the restricted class of musical sound'. More recently, Piszczalski and Galler [Piszczalski 1977, 1979, 1981] have, according to Moorer [Byrd 1984, p.78], 'refined monophonic music transcription to a fine art'.

Further work by Chafe [1982], Foster [1982] and others, used artificial intelligence techniques to automatically determine clef, key and time signatures, and enharmonic notation. However, Piszczalski and Galler [Piszczalski 1979, p.203] have asserted that 'the state of the art is nowhere near approaching the successful automatic transcription of polyphonic music recorded on a single track.'

Hence, it can be concluded that recognizing music from a

soundtrack combines all the problems associated with using a directly-connected instrument for input with those involving spectral analysis and psychoacoustics.

2.2.2.3 The compromise solution to the input problem

From the previous discussion it will be realized that, except in very restricted circumstances, methods which appear ideal do have flaws which prohibit their use as sole input devices. Hence, whether a musician or non-musician is entering the music data, the problem becomes one of optimizing the man-machine interface, with any musical ability on the part of the operator serving to speed this interaction. The main types of peripheral device available to any user for entering music data are:- QWERTY keyboard, digitizer (graphics tablet), and pointer (light-pen/mouse/joystick/tracker-ball).

As has been previously stated, the three basic types of information present on a page of printed music (pitch, rhythm and other symbols) tend to associate themselves with particular peripherals, depending to a great extent on the type of music being encoded.

The QWERTY keyboard is always available, which is its main advantage. With suitably defined function keys and/or an overlay together with carefully designed software, the ordinary keyboard can be quite successful, although it is still physically limited by the number of keys. Some systems still rely on the QWERTY keyboard for direct input of alphanumeric music-representational

data, although more use is being made of menu-driven systems with on-screen icons [Hewlett 1988].

The graphics tablet has been separated here from other 'pointing' systems because, where pitch is concerned, it has a unique advantage, i.e., the actual printed score (assuming one exists) can be placed on the tablet (a page at a time) and the noteheads picked out with the pen or stylus, a method successfully used by Wittlich et al. [1977, 1978a]. Hence, this is the only 'pointing' system which uses the score directly. This speeds up entry considerably because it eliminates the repeated movement of the eyes from score to screen. Alternatively, the tablet can be divided up (using an appropriate overlay) into regions, each representing a particular symbol, pitch, etc., so that all aspects of the music may be entered in this way.

The different types of pointer - light-pen, mouse, joystick, tracker-ball - work in a similar way, in that they select symbols from a menu, but vary in their ergonomic convenience. Use of these devices facilitates screen feedback, hence the adoption of abbreviations (e.g., for repeated pattern entry) or short-cutting techniques, such as having various permutations of chord patterns or arpeggio figures available in the menu.

2.2.2.4 Practical assessment of input methods

The following list gives a general view of which peripheral

best suits each category of music information:-

1. Pitch

- i) { Digitizing tablet (tracing the score with a stylus)
Organ keyboard (depending on the complexity of the music
and the musical ability of the operator)
- ii) Pointers

2. Rhythm

- i) Pointers (+ menu of patterns on screen)
- ii) Digitizing tablet (+ menu of patterns)
- iii) Organ keyboard (+ metronome click-track)

3) Text, slurs, etc.

- i) Pointers or QWERTY keyboard
- ii) Digitizing tablet

The order chosen for 2 i /ii and 3 i /ii above is determined by the greater inconvenience involved in moving between score, screen and tablet as opposed to score and screen.

In a test undertaken by the author, the graphics tablet method of entering letter names of pitches has yielded results of approximately 90% accuracy. The opening three lines of the flute part for J. S. Bach's Sonata in C were scanned three times each, with individual lines averaging 48 notes taking about 30 seconds. The results were obtained using a graphics tablet having a resolution of 0.001", i.e., 1,000 points per inch, or approximately 60 points between stavelines.

Taking into account the improvements that could be made to the system used, the results were quite promising. Modifications might include using a cursor with a lens and cross-hair instead of the pen utilized in the test system, plus some form of guidance as to the proximity of the pointer to one of the horizontal pitch lines (i.e., stavelines and centre-lines of spaces) in order to permit re-entry of wayward values. It has to be accepted that in general the stave will not be horizontal and any calculations involving vertical measurements must take this deviation into consideration. Although the bowing of stavelines (mentioned as a problem by Wittlich et al. [1978a]) was not encountered, it must be planned for when indicating the position of the stave (i.e., not only indicating end-points). For a non-musician, a 100-notes-per-minute, 90% accurate system for entering pitch values (letter names only) might form a valuable part of a practical set-up. Wittlich et al. [1978a] cited user-friendliness and speed as the most favourable features of this sort of system.

A deciding factor that emerges here is the type of music involved. For example, the above test was carried out on a sample of Bach, which consisted of more-or-less continuous semiquavers, making entry of the rhythm values particularly easy for a 'mouse and icons' or similar system, with good repeat facilities. In certain cases, however, the pitches also form patterns and this may be an example where a mouse could be used to achieve results faster, picking from a limited set of previously defined patterns, rather than entering all pitches via the graphics tablet or organ keyboard. On the other hand, types of twentieth century music which dispense with the key signature and employ numerous

accidentals could not beneficially be entered using a system where one method is used for entering the letter names of pitches (i.e., organ keyboard or tracing the score on a graphics tablet) and another is used for specifying the desired accidentals. Thus, the choice of method can be seen to be related to both the type of information being encoded (pitch, rhythm or other symbols) and the style of the music.

During the design of Music Representational Languages, much effort has been expended to support abbreviations, for instance to avoid repeated encoding of constant rhythm values or to provide a means of tagging certain patterns (of rhythms or pitches) so that these can easily be recalled. However, this feature must surely be most easily implemented by the software controlling a 'pointer and icons' system rather than the syntax of the M.R.L. (Music Representational Language). The only possible exception to this might be where the QWERTY keyboard is used to enter raw data, where minimizing the number of keystrokes involved in encoding is paramount. In this case, a cursor-key-controlled 'pointer and icons' system may still be faster and will certainly be easier to learn and use [Carter 1984]. As the abbreviated M.R.L. data would almost certainly have to be expanded to the 'long-hand' version at some stage (as in user-DARMS to canonical-DARMS discussed in section 2.3.1.1), program simplification would be achieved by having the user-interface software output standard M.R.L. data. Abbreviations in M.R.L.'s are covered in Section 2.3 - REPRESENTATION. Optimization of the man-machine interface is discussed, for example, by Card, Moran and Newell [Card 1983] in the context of a formal research project, and by Freeman [1986] in

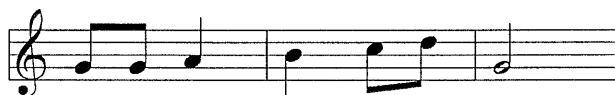
a personal assessment of one particular application (word-processing).

At this point, mention should be made of Armando Dal Molin and his purpose-built music-entry terminals. Dal Molin's significant contribution to computerized music-setting and printing is covered in numerous publications [Dal Molin 1973, 1975, 1976, 1978] [Sargeant 1971]. His Musicomp (PCS 500) terminal [Dal Molin 1978] utilizes a combination of pitch keyboard (i.e. four stacked octaves of white keys) and music-orientated QWERTY keyboard built side-by-side into the console. This permits use of the left hand for Pitch and right hand for Character (symbol) and Spacing, hence the acronym PCS. Good on-screen feedback and editing facilities are significant features of the system, which produces near engraving-quality output on a phototypesetter.

2.3 REPRESENTATION

In addition to an input method, a means of internally representing the score is required, as all or part of the information present in the score must be stored electronically. A score can be stored as a graphic image, i.e., as an 'electronic photograph', so that the holding computer has no knowledge of the meaning of the symbols in the image, but this method is of limited practical use. Alternatively, the information contained in the score can be stored using a Music Representational Language (M.R.L.), enabling reconstruction of the score using appropriate software, albeit with inevitable slight differences in layout.

A Music Representational Language is a symbol system, normally using ASCII characters (but sometimes binary or decimal numbers) to represent musical pitches, rhythms or other miscellaneous notational symbols. For example, the letters A to G might represent the pitches of the same names, and the numbers 2, 4 and 8, the durations of a half, quarter and eighth note (minim, crotchet and quaver). Hence, using this simple and restricted M.R.L., the following extract would be written G8 G8 A4 B4 C8 D8 G2.



Obviously, for a useful M.R.L., more symbols would be required to represent octaves, clefs, barlines, rests, dotted notes, slurs, etc. Another factor emerges here, that is, the amount of decision-making which should be built into the 'score-reconstruction' software, instead of being included in the M.R.L. For example, in the music extract above, the pairs of quavers are beamed, but this is not indicated in the M.R.L. data; a score reconstruction might appear with separate quavers. Thus, either another symbol could be included, indicating beamed notes, or an automatic beaming facility could be included in the score-reconstruction software. The latter might cause problems, however; for instance, where it could not be determined automatically how, or even if, a number of notes should be beamed.

Once the score has been converted to M.R.L. data, it can be analysed by software, edited, performed electronically or reconstructed for printing. The hardcopy can be in the form of proofs or finished artwork, consisting of score, separate parts, or piano reduction. Thus, assuming that an M.R.L. data version of a score is desirable, the researcher has the choice of either using an existing M.R.L. or creating his own.

Unfortunately, in the past, music researchers have chosen, for several reasons, to invent their own M.R.L.'s, and continue to do so (see [Gourlay 1986]). In most cases, the M.R.L. was tailored to the particular requirements of an individual research project, and as the nature and scope of projects differed, so did the requirements of an M.R.L.. This variety created the problem which still exists today, i.e., the lack of a standard encoding scheme for representing music scores. The recently established Musical Instrument Digital Interface (M.I.D.I.) standard provides the equivalent for musical sound. The pressing need for a standard has frequently been stressed by authors writing on the subject of computers and music (e.g., [Lincoln 1970b] [Morehen 1979]), but researchers who have encoded large quantities of data using their own particular M.R.L. are understandably averse to re-encoding the information. This has meant that a barrier exists between workers in the field which obstructs the transportation of data and software for analysis, printing etc. Recently, a task group (the Music Information Processing Standards Committee) formed under the auspices of the American National Standards Institute has been asked to propose a standard for the interchange of musical

information. It is intended to use only printable characters as an extension of SGML (Standardized General Markup Language), the code which covers production aspects of text publication. The principal document produced by the committee includes an outline for the standard [MIPS 1988]. Also, a working group of the Music Library Association is currently examining the possibility of using encodings of music in library cataloguing [Hewlett 1986b].

Irrespective of whether the researcher is choosing an existing one or creating his own, various attributes of an M.R.L. have to be assessed; in particular the scope (i.e., completeness), structure, (hierarchical or sequential), and efficiency (i.e., compactness). Also to be considered are the use of mnemonics, number of passes, availability of software for syntax/semantic checking or translating, existence of a shorthand version, and compatibility with existing facilities.

2.3.1 Existing M.R.L.'s

Much of the literature on computers applied to music relates to the subject of particular M.R.L.'s [Heckmann 1967] [Brook 1970a] [Lincoln 1970a]. However, as few as six have been used in significant research, or have been specified thoroughly enough for practical use. A comprehensive survey of M.R.L.'s has been produced by Boody [1975], together with a more detailed analysis of six of these which met his list of criteria deemed necessary - but not sufficient - for a useful language. From consideration of these evaluations, three M.R.L.'s emerge as the most suitable for general use, with a definite ranking of DARMS, MUSTRAN, ALMA.

2.3.1.1 DARMS: Digital Alternate Representation of Musical Scores

A large proportion of the literature on computers applied to music mentions DARMS at some point. Originating in the 1960's, the DARMS Project has involved work by Stefan Bauer-Mengelberg (the M.R.L. itself), Raymond Erickson (Syntax-checker), Anthony Wolff and Bruce McLean (user-DARMS to Canonical-DARMS translator, [McLean 1980]), David Gomberg (score-layout programs) and Melvin Ferentz (production of printed score). There are three main papers [Bauer-Mengelberg 1970] [Erickson 1975, 1983] which discuss DARMS in detail as well as three publications [Gomberg 1975, 1977] [Wolff 1977] covering aspects of representation and music-setting which form part of the DARMS project, with its aim of producing publication-quality music from DARMS data (See also [Gomberg 1972] [Wolff 1972] [Feldman 1973] [Bauer-Mengelberg 1972, 1974a, 1974b] [Erickson 1977]). A user manual has also been produced [Erickson 1976].

DARMS was specifically designed [Erickson 1983 p.176] 'to capture accurately all the information provided by the composer, but not those details of layout within the province of the engraver or autographer.' DARMS has become the most widely used M.R.L. because it can be used to encode most music published since c.1600 which uses Common Musical Notation (C.M.N.).

The encoder can make use of extensive abbreviations which are permitted in 'user-DARMS' but these are expanded by the 'Canonizer' software into their complete version, known as

'Canonical-DARMS'. Hence, there may be several versions of a score in user-DARMS, but there will be only one Canonical-DARMS representation. Briefly, the representation uses numbers for pitches (21 to 29 cover lines and spaces on the staff), letters for rhythm-values (Q, E, S, etc = Quarter, Eighth and Sixteenth notes respectively, i.e. crotchet, quaver and semiquaver) and other ASCII characters for miscellaneous symbols, e.g.:(# , - , *) = (#, b, q) respectively. Chords and polyphonic music are catered for, the latter by a method called Linear Decomposition Mode, i.e., encoding one voice per pass over the score.

2.3.1.2 MISTRAN: Music Translator

MISTRAN [Wenker 1969, 1970, 1972a] was developed by Jerome Wenker, originally for ethnomusicological purposes, but the revised version, MISTRAN II [Wenker 1972b, 1974, 1977] includes more 'art-music' notation, representing C.M.N. almost as comprehensively as DARMS.

MISTRAN (II) uses more mnemonic symbols than DARMS and has better software support (translator and utilities). The Indiana University Computer Music System [Wittlich 1978b], which incorporates Donald Byrd's SMUT (System for Music Transcription) software [Byrd 1984] uses MISTRAN as its Representational Language. It was chosen because of its mnemonic code, relative completeness and existing translator and syntax analyser. Both the original MISTRAN and MISTRAN II have been described in detail by Wenker [see Wenker 1969 to 1977] while details of the numerous MISTRAN utility programs now available at Indiana University can

be found in [Hewlett 1985].

2.3.1.3 ALMA: Alphanumeric Language for Music Analysis

ALMA [Gould 1970], which can cope with most C.M.N. (including polyphony), evolved from the 'Plaine and Easie Code' [Brook 1964, 1965, 1970b] invented by Barry S. Brook and Murray Gould, which while sometimes used (see [Rösing 1985]), is limited to monophonic music representation. ALMA supports abbreviations, optional multi-pass encoding, user-determined order of encoding and user-defined representational symbols. ALMA also supports a novel feature which helps with encoding repetitions, i.e., cyclic duration definition. This means that a recurring rhythmic pattern can be encoded once only and it will automatically be cyclically applied to following groups of the same number of notes.

A common problem with both MUSTRAN and ALMA is the use of letters to represent pitches, for although this seems appropriate at first (being suitably mnemonic), it means that a separate octave indicator has to be used. For example, in ALMA, the apostrophe (') is used once for each octave above middle C and commas (,) correspondingly indicate octaves below middle C. Thus, a passage of music which alternates across the boundary between two octaves will, when encoded, consist of numerous commas or apostrophes compared to the number of actual pitch symbols. This inefficiency is overcome in ALMA by an abbreviation facility which allows the encoder to indicate only a change of octave relative to the present one (+ or - a fourth relative to the present note). Obviously, this problem does not occur in DARMS, with its numeric

pitch-representation system.

2.3.2 M.R.L. structure

The structure of the M.R.L. is for the most part determined by the method of encoding polyphonic music. Various ways of referencing the notes in multi-part music have been adopted or proposed (e.g., [Clements 1980a, 1980b] [Maxwell 1983, 1984]).

One method is to encode voices separately with a tag of some sort to indicate which is which, but this can be wasteful if a composition consists almost entirely of one voice with just a few chords, since the subsidiary voices will have to be encoded throughout. Alternatively, encoding can be orientated around vertical 'time slots', so that all notes occurring simultaneously may be referenced together. Different voices then 'switch in and out' as and when they are required. Both Clements and Maxwell have favoured the latter approach, defining everything in the time domain, because the system thereby avoids any constrictions which would arise through the use of a musical hierarchy. Clements [1980a] also describes a 'neutral' M.R.L. implemented at the University of Western Ontario, which contains enough information in its data to facilitate ready conversion to either a 'sound output file' (for performance) or DARMS format (for printing).

2.3.3 The Editor

The minimum features of an editor have been formalized by Clements [1980a], as have the varieties of operational scope

needed [Buxton 1980, 1981]. Basically, the editor requires a data pointer, together with the following functions, the operation of which should be self-evident: delete, insert, change, transfer, search, substitute and transpose. The five categories of scope defined are: simple, block of time, local attributes, contextual attributes and named structural entities. In order, these refer to single note or entire score, notes within a certain time interval, notes encompassed within limits of pitch and duration, a note or notes within a certain musical context, and notes of a defined motif or theme.

Various arguments have been put forward supporting different structures for M.R.L.'s; when consideration is given to the incorporation of an editor into the system, however, opinions [Maxwell 1984] [Clements 1980a] come down in favour of a sequential, time-ordered structure. This facilitates access to the data by the editor because information which is close together in the notated score will also be close in the Music Representational Language form.

It should be stressed that when entering information, the user can be buffered from the raw M.R.L. data by the use of certain types of user-interface, as described in sections 2.2.2.3 and 2.2.2.4. Hence, different assessment criteria must be applied to M.R.L.'s when data is input via a QWERTY keyboard, compared to, say, a mouse and icons system. When using the former, as has been stated previously, minimizing the number of keystrokes is of paramount importance, so abbreviations (shorthand) and mnemonics (for ease of use) would be prime factors for consideration.

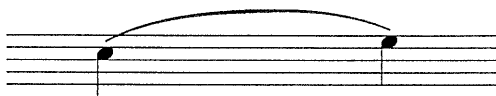
If another means of input is being employed, however, e.g., organ keyboard or graphics tablet, then comprehensiveness and efficiency are perhaps the most relevant features to be considered.

The issue of translation seems to be gaining in importance at present, as researchers accept the fact that there is no standard method of representing printed music, and opt for encoding data in as crude a form as possible so that it can then be translated into whichever M.R.L. is later required. If only pitches and rhythms are required initially (perhaps so that some form of analysis can be undertaken), and then later printed scores are required and only DARMS-compatible printing software is available, then it should be reasonably easy to convert the encoded data into the DARMS format and at the same time add previously omitted information. However, despite solving the problem of researchers' tenacious defence of their own M.R.L.'s (i.e., this approach allows them to retain their own data format), the result is a proliferation of translation software.

2.3.4 Problems concerning score representation in the context of printing

One example of this has already been mentioned, i.e., whether to indicate beaming in the M.R.L. or to try to formalize the rules for beaming of notes and to incorporate this knowledge in the score-reconstruction software. To take another example, the slur

shown below



is 'attached' to the two notes when included in the M.R.L. data, but its exact position and curvature will probably be determined by the music-setting software. Some M.R.L.'s do, however, make provision for stem direction (for example) to be encoded (e.g., U and D for up and down stem respectively) if desired.

A detailed discussion of some of the problems involved in representing all the complexities of music notation can be found in Wolff [1977]. For example, sometimes too many notes are present in a bar, either because the notes are an appoggiatura written in small notation or because a triplet sign has been omitted. These features have to be indicated in some way to prevent syntax-checking software producing an error. Another problem relates to horizontal positioning, where notes to be sounded simultaneously are of a similar pitch and must be separated out horizontally; this separation can also lead to 'too many notes in a bar' as well as variations in layout.

In coping with the above cases there is a trade-off between the interpretative ability of the encoder, the knowledge-based rules programmed into the score-reconstruction software and the graphical information included in the M.R.L. Donald Byrd [Byrd 1984] asserts that fully-automatic reconstruction of high-quality music notation is not possible without artificially intelligent

software for this purpose. As this is not available at present, a compromise has to be reached; hence the trade-off mentioned above.

Most of the problems concerned with score-representation seem to be caused by the transfer from two dimensions (pitch and time) to the single-dimensional string of ASCII characters. These difficulties are compounded by the fact that there is not always a one-to-one correspondence between music-notational symbol and ASCII character(s). This is due to the graphical variations which can occur in some musical symbols (e.g., slurs).

2.4 RECONSTRUCTION

It is the actual hardware used which has the most influence on reconstruction. Once the master copy of the printed page has been produced, it can be mass produced by traditional means, such as offset lithography. The software of a music printing system can be designed to be device-independent, at least within certain categories of printer. It is easier, however, to convert from a vector-image (or random-scan) construction scheme to a raster-scan format than vice versa. Vector-drawing image construction means building up the image by drawing line segments (vectors); raster-scan implies plotting a large number of points while making horizontal sweeps over the imaging area. In the former case, small segments may not be drawn accurately and producing dots can prove to be a problem, whereas with the latter it is the number of points per unit area (i.e., the resolution) which is crucial to producing a good image (which appears not to be made up of

individual dots).

Numerous types of printer are available for producing hardcopy computer output. Music printing systems have tended in the past to use three main varieties, the dot-matrix printer, plotter and phototypesetter. The primary features which determine these choices are price, resolution and speed. The printers' best attributes are shown by category in the following table. The phototypesetter, for example, provides the best resolution and speed at the worst (= highest) price.

	price	resolution	speed
dot-matrix	1	3	2
plotter	2	2	3
phototypesetter	3	1	1

The dot-matrix printer is widely available and very popular because of its price and versatility. It can produce scores at a resolution of up to approximately 360 dots per inch (d.p.i.) which is adequate, although beams which slope only slightly will appear as a 'staircase' and slurs will not be smooth. These disadvantages can be minimized by producing oversized originals and then using photoreduction at the production stage. More often, though, the intention is to use the dot-matrix printer for producing draft copies for proof-reading or one-off prints for use in an educational situation or by a composer. Often the dots which constitute the image are large compared to the 'grid' on which they can be positioned, so that adjacent dots overlap and, for

example, a line two dots wide would be less than twice as wide as a line of single dot thickness.

In the past, the plotter has been by far the most widely used output device for computer printing of music within the context of research projects (see section 2.5). Its two main forms are the X-Y flat-bed pen plotter and the drum plotter. In the former, the pen travels over both axes, whereas with the latter the pen moves over one axis only and the paper moves over the other. Although the plotter is relatively slow, it can resolve up to a thousandth of an inch, but then suffers from a problem similar to the dot-matrix printer in that the ultimate resolution is decided by the pen being used, and not by the 'grid' upon which it is positioned. Again, photoreduction can be used to improve the perceived resolution and assist in eliminating 'staircase' effects.

The phototypesetter also exists in two forms: mechanical and digital [Seybold 1983], but the latter is rapidly taking over from the former. Both types produce output on film but the mechanical typesetter uses templates and an optical system to produce very high quality images with an accuracy in the region of +/- one thousandth of an inch. The use of templates dictates that the character-set is built into the hardware. This restricts the number of symbols to less than that needed to cover all orientations of beams and slurs, and is less flexible than the digital approach. In a digital typesetter, the number of characters/symbols available is limited solely by the on-line storage capacity. So, although the digital typesetter is the more

expensive variety (tens of thousands of pounds), it has enormous flexibility and is able to produce images of very high quality (approx. 2500 d.p.i.) making it the ideal music printing device.

More recently, other designs of printer have been developed and refined and hence have become available for music printing [Weber 1986a, 1986b]. Specifically, these are varieties of non-impact machines, such as thermal transfer, electro-erosion, electrostatic and xerographic printers.

Thermal transfer printers are capable of approximately 300 d.p.i., an example being the IBM Quietwriter 7 typewriter/printer, but the short life-span of the ribbons used leads to high running costs.

Electro-erosion printers (such as the IBM 4250) produce up to 600 d.p.i. (low typeset quality) by using a high-density printhead to burn away the metallic surface covering a black backing paper, which is then used to produce final output on film.

Electrostatic printers produce a resolution of up to 400 d.p.i. Their print quality and contrast, however, are not as good as the xerographic printers described below. A disadvantage of electrostatic printers is their requirement of special paper.

Of all xerographic (or electrographic) printers, the laser printer is, at present, the most popular form. It is being used widely for music printing (see section 2.5) where it is seen to benefit from some of the advantages of the phototypesetter (high

speed and resolution) but with none of the disadvantages of the plotter and dot-matrix printer. Other varieties of xerographic printer use a different light source such as light-emitting diodes, or a liquid crystal shutter to control the light. Working on principles similar to those of a photocopier, the modulated light source directed onto a rotating drum produces an image on the charged drum surface. This is then used to transfer toner onto the paper, where it is heat-fused. A diode or liquid crystal shutter as the light source or controller, respectively, gives the printer greater reliability because it cuts down on moving parts. Speeds for laser printers vary between six and 200+ A4-size pages per minute, prices are from £1,000 upwards, and maximum resolution is about 600 d.p.i.. Duplex printing (i.e. on both sides of the page) and A3 paper-handling - both important features for music printing - are now becoming available in cheaper machines.

Normally, assuming a laser printer (or similar) has the facility to address all points over its imaging area, the information actually transmitted over the interface between host computer and printer is a coded description of the original image. This produces significant data compression compared to transmitting a complete bit-map representation. A raster image processor (R.I.P.), normally contained in the printer, converts the transmitted code into a raster image and controls the marking engine itself. It is the R.I.P.'s own command language which determines the text/graphic printing capabilities of any particular printer. There is a similarity between the laser printer and phototypesetter in that, in both cases, the host computer has merely to transmit information regarding which symbol

(character) is to be printed, where on the page, and perhaps in what orientation. The printer can then construct the bit-map form of the image and thus offload a large amount of work from the main computer. Currently, the effective standard for this type of coded data transfer between computers and printers is Adobe Systems' 'Postscript', although other page description languages (PDL's) are in use, for example Xerox's Interpress. In practice, this means that the same data can be sent to an appropriate laser printer or phototypesetter, and the only difference in the output image will be the change in resolution. Also, 'Display Postscript' is now becoming available, providing even more device-independence, by enabling a Postscript encoded image to be displayed on-screen.

2.5 APPENDIX

The following table can be viewed as an enlarged version of the survey given in Donald Byrd's thesis 'Music Notation by Computer' [Byrd 1984]. References have been added pertaining to systems which Byrd mentions. Information on systems which were recent at the time of his writing, has been expanded upon, and details of some new systems have been added. Also, the information is presented in a clear tabular form. Ideally, the same features of each system would have been examined to facilitate direct comparison; the systems vary so much, however, that this is not possible, especially considering the varying amount and age of information which is available. Examples of output from significant systems are to be found in [Clements 1980a] and [Hewlett 1985, 1986b, 1987, 1988]. Where the information provided

is based on [Byrd 1984], the subjective descriptions of output (e.g., 'high-quality' scores) have been retained and where the current author's opinion is being expressed, a similar scale has been adopted, i.e., low or poor, adequate, reasonable, high, very high or very good, excellent or engraving-quality.

As the price of technology falls, significant developments are occurring at a rapid pace. For example, the hardware used in the Mockingbird system developed at Xerox's Palo Alto Research Center, deemed 'prohibitively expensive' in 1984, may in the not-so-distant future come within reach of most music publishers' budgets, if not those of music copyists. More music printing software is becoming available for popular microcomputers, which is having a significant impact, especially where the Postscript page description language is used, with its aforementioned flexibility. The possibility of proofing output on a laser printer and then using a bureau service to produce final typeset material *from the same data* is proving attractive in music production (as well as general graphics applications) because, while giving access to top-quality output, it removes the need to invest heavily in typesetting equipment.

TABLE OF MUSIC PRINTING SYSTEMS

Name of system	Instigator(s)	References
AMADEUS	Kurt Maas	[Maas 1985]

Amadeus uses polyphonic real-time input by organ keyboard

and/or QWERTY keyboard. Facilities for playback and transposition are available, and editing is very versatile giving varied layouts, including text. The system is MIDI-compatible, and, connected to a laser phototypesetter, gives excellent quality. The notational vocabulary is comprehensive and layout facilities cover several parts to a stave and parts crossing from one stave to another. The system is used by its originators to provide a music-setting service (used, for example, by Schotts).

C.C.A.R.H. System Walter B. Hewlett [Hewlett 1985,
1986a, 1986b, 1987, 1988]
[Selfridge-Field 1986b]

The system of the Center for Computer-Assisted Research in the Humanities runs on the Hewlett Packard 1000 computer using the IBYCUS operating system. Input is by organ keyboard (each voice separately) with a playback facility (via any MIDI-compatible synthesizer) available. Draft-quality output is by dot-matrix printer, although a limited Hewlett Packard Laser Jet printing option is available. The system is aimed at the creation of a music database (initially the works of Bach and experimentally those of Corelli, Legrenzi and Handel) for musicological and educational purposes.

COMPOSER'S Syntauri Corporation [Aikin 1983]
ASSISTANT

Composer's Assistant uses real-time input via a synthesizer to an Apple II computer, with output by dot-matrix printer.

INTERACTIVE MUSIC	Lippold and	[Schmid 1984]
SYSTEM	Dorothea Haken	[Scaletti 1985]
	(C.E.R.L.-Illinois)	[Hewlett 1985, 1986,
		1987]

Based on the PLATO computer system (using the 'C' programming language), the Interactive Music System is part of the computer-based music education system at the University of Illinois. Input is via an organ keyboard with alphanumeric and graphic editing and playback facilities available. Up to 60-part scores can be produced, with a wide range of notational symbols (including n-tuplets) available. Draft-quality output is provided by a dot-matrix printer and laser printer output is available via an Apple Laserwriter.

LA MA DE GUIDO	Llorenç Balsach	[Balsach 1986]
		[Guido 1988]

La Ma De Guido, a software package for the IBM PC, is used by its originators to provide a music-setting service. Input is by QWERTY keyboard or MIDI synthesizer and output is via a plotter. Flexible editing and user-defined symbols are available, as is transposition and the facility to produce parts from a score. A limited version restricted to four voices and two staves per system is also available, as are test programs for either package. A separate score performance module permits playback of up to eight voices via a MIDI synthesizer, with control over tempo and other parameters.

LUDWIG	William Reeves	[Reeves 1978]
	and William	[Buxton 1978a,
	Buxton (et al.)	1978b, 1979]

Ludwig is a score-editing system developed as part of the University of Toronto's Structured Sound Synthesis Project (SSSP).

MANUSCRIPT	Rebecca Mercuri	[Mercuri 1981]
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Manuscript is a music notation system for the Apple II using menu-input and editing.

McLEYVIER	David McLey	[McLeyvier 1982]
	(SYNTRONICS)	[Gilbert 1982]
		[Spiegel 1983]
		[Hewlett 1987]

The McLeyvier uses input via organ keyboard (either real or non-real time) or M.R.L., with other features similar to the Synclavier. The system is now owned by Syntronics of Toronto.

MOCKINGBIRD	John Turner Maxwell	[Roads '81]
	III & Severo M.	[Maxwell 1982,
	Ornstein (Xerox PARC)	1983, 1984]
		[Ellis 1984]
		[Hewlett 1986b]

Mockingbird uses real-time input via Yamaha CP30 keyboard (piano music only) with powerful editing facilities to convert

piano-roll notation to C.M.N. using menus and a mouse. Mockingbird runs on the Xerox Dorado (Xerox 1132) in Mesa and produces very good quality output via a laser printer. A playback facility is incorporated.

MP-1 MINIPRINTER Yamaha Inc. [Yamaha 1983]

The MP-1 is a synthesizer with built-in pen plotter (using 2 1/2" wide paper) which prints melody lines only (i.e. monophonic).

MPL - NOTATE Gary Nelson [Nelson 1973a, 1977]

MPL - NOTATE is part of an integrated suite of music programs (MPL = Music Program Library) written in APL on a Xerox Sigma 9. Input is by QWERTY keyboard with plotter output of fairly high quality scores, but with only one voice per stave.

M S / SCORE Leland Smith [Smith 1973,1979]

Passport Designs Inc. [Bowles 1974]

[Hewlett 1985, 1986b]

[SCORE 1988]

M S / SCORE is a well-known system using the researcher's own encoding language to produce multiple voices per stave. Feedback and interaction are essential features, permitting the system to cope with music of unlimited complexity. The use of vector graphics permits output via nine or 24-pin dot-matrix printers or any Postscript device, including the Apple Laserwriter and

SMUT (+MUSTRAN) Donald Byrd [Byrd 1970, 1971 1972,
1974, 1976, 1977, 1980, 1984]
[Hewlett 1986b, 1987, 1988]

Input to SMUT is via M.R.L. (MUSTRAN) or organ keyboard (in conjunction with a translation program). High-quality output is produced on a plotter, although the software is designed to be independent of output device. Important features of the system include portability and routines for rhythm clarification and automatic beaming. SMUT allows one or two voices per stave and multiple staves. The software is currently being adapted to run on the Macintosh using Adobe Systems' 'Sonata' music font (a library of approximately 200 symbols) under the product name Nightingale.

SOUNDCHASER Passport Designs Inc [Soundchaser
NOTEWRITER/ 1982, 1984]
POLYWRITER [Ellis 1984]

Polywriter uses real-time organ keyboard (MIDI-compatible) input, played along with a click-track, giving resolution to triplet semiquavers. Eight score formats are available (from single stave to 40-part orchestral scores) with a 2700 notes-per-page capacity. Fully polyphonic notation is allowed, including ties, beams, split stems, double-sharps and flats and 8va, plus 40 automatic instrument transpositions. Up to 28 individual polyphonic parts can be recorded, with fairly comprehensive editing facilities, including adding text. The software runs on Apple computers with the Soundchaser keyboard (or similar MIDI-compatible) and produces adequate output on a

dot-matrix printer. Notewriter was a monophonic predecessor.

STAVEWRITER Fairlight Corp. [Ellis 1984]

Stavewriter is a software package for the Fairlight Computer Music Instrument which allows high-quality printing of music from either real-time performance or a dedicated M.R.L.. As of 1984, only monophonic C.M.N. was possible (later four parts were to be available), or all eight parts of real-time input could be printed in 'simplified notation'. Options available include adjustable stave proportions and positioning, proportional spacing, transposition and automatic calculation of irregular rhythmic groups. The system is tailored to a specific plotter (the H.P. 7475A), which produces very good output, although the proportions of some symbols are not quite correct and spacing is abnormal in some cases.

SYNCLAVIER New England Digital [Synclavier 1983]

MUSIC PRINTING Corp. [Ellis 1984]

OPTION [Talbot 1988]

The Music Printing Option for the Synclavier uses either synthesizer or dedicated M.R.L. ('SCRIPT') input, with output of high quality by laser printer or phototypesetter (optionally by dot-matrix printer). One or two voices per stave (including chords) are available, as is feedback, but editing possibilities are limited. Notational vocabulary includes n-tuplets, dynamics, articulation marks, instrument names, text and page or bar numbers. The system is currently undergoing substantial revision

and enhancement.

THEME - Mark Lambert [Lambert 1983]
THE MUSIC EDITOR [Hewlett 1987, 1988]

THEME is a system for use in musicological applications as well as printing/ editing, etc. It handles up to 16 polyphonic voices and eight notes per stem, using QWERTY keyboard cursor-control input. Beams and stem-direction are produced automatically and a wide variety of notation is available. Ornamental passages can be freely inserted while maintaining vertical alignment in the printed score. The software runs on the Apple II, TRS-80, or IBM PC producing adequate quality output from a plotter, dot-matrix or laser printer. As of 1983, the facility to produce parts from a score was mentioned as being under development. Sound playback is possible via a MIDI synthesizer.

TOPPAN SCAN-NOTE Toppan Printing Co. [Toppan 1984, 1988]
[Hewlett 1986b]

The Scan-Note system described above was taken over by the Japanese printing company Toppan Ltd. and became the Toppan Scan-note system. Input as above. Output is via dot-matrix printer for proof-reading (enabling error-correction and adding of instrument names, dynamics etc., using a graphics terminal), and laser-typesetter for engraving-quality final copy. Facilities available include parts from a score, transposition, alterable layout and format. Available examples are conservative, so it is

difficult to assess the versatility of the system as regards quintuplets, septuplets, appoggiaturas, etc. Although multiple staves (single line per stave plus chords) are possible, there is no evidence of multiple voices on one stave. The system is in use commercially (for example, by Bärenreiter Verlag), but is also available running on the Apple Macintosh II.

Norbert Böker-Heil [Böker-Heil 1972]

A system which uses ALMA input and plotter output in producing single-voice-per-stave scores of good quality.

Donald Cantor [Cantor 1971]

This is early work, based on that of W.B. Barker, limited to two voices on two staves using menu-entry and running on a PDP-11 computer and four cathode ray tubes. The system has a playback facility.

A-R Editions Inc. [A-R Editions 1985]
[Hewlett 1986b]

A-R Editions' system is part of a commercial operation, producing engraving-quality output from a phototypesetter, using QWERTY keyboard input of a dedicated M.R.L. (a hybrid of FASTCODE - developed by Thomas Hall at Princeton University - and DARMS). The software checks syntax and does automatic formatting, positioning of stems, beams, slurs, etc. Automatic extraction of parts from a score is possible. It is hoped that a large databank

of encoded music can be created. The only examples available show no evidence of a multiple-voices-per-stave capability. The system is used both for A-R Editions' own publications and by other music publishers.

Lejaren Hiller [Hiller 1965]

This is early work on the setting of music using an ILLIAC I computer and Musicwriter typewriter for input and output, producing high-quality, single-voice-per-stave scores, but limited in many ways.

Prentiss Knowlton [Knowlton 1971, 1972]

This system uses both types of keyboard for input of pitch and rhythm (real-time), i.e., an electronic organ linked to PDP-8 computer, producing limited output of poor quality.

(for M.I.T. William Kornfeld [Kornfeld 1980]
LISP machine)

This system uses M.R.L. input or real/non-real time input by organ keyboard with good editing made possible using a mouse but on a bit-map representation (i.e., in image space).

Harry Lincoln [Lincoln 1970a]

This system uses DARMS input and produces low-quality output consisting of limited complexity music on a line printer

with a music character print chain.

Gary Wittlich (et al.) [Wittlich 1973a,
1973b, 1977, 1978a, 1978b]

This system uses real-time organ keyboard and graphics tablet for input but the only output samples available are of poor quality.

3. Pattern Recognition Of Binary Images

3.1 BACKGROUND

Given the large amount of work that has been undertaken with regard to manipulating printed music using the computer, as surveyed in chapter 2, it is apparent that there is a significant need for an automatic acquisition system. The large number of applications which this would make possible include automatic production of individual players' parts from an existing printed score, editing of existing printed material and production of braille music scores. The possibilities will be detailed and discussed in section 3.3.

It has been seen in chapter 2 that music data entry can usefully be achieved either by using an automatic pattern recognition system or by optimizing the man-machine interface of an operator-driven system. For purely economic reasons the former is preferable, especially when considering large scale conversion of existing printed material into computer-manipulable form. It is interesting to compare a parallel project in the field of text. The production of the Thesaurus Linguae Graecae (a database of classical Greek literature containing 62 million words) was achieved using *manual* entry in South Korea and the Philippines [Helgerson 1988], similarly, the electronic form of the New Oxford English Dictionary (N.O.E.D.) was produced manually [Weiner 1987]. It must be borne in mind, however, that the availability of people skilled in fast entry of text using a standard QWERTY keyboard is

far greater than those skilled in entry of musical information, by whatever means. Automatic text reading machines were investigated as an option for the N.O.E.D. project, but rejected on the grounds that the wide range of fonts and poor quality of the images involved were beyond the scope of what was then available [Weiner 1987], and, indeed, would still present a formidable challenge today. Also to be considered, following the recent growth in use of desktop publishing, is the availability of desktop scanning equipment and in conjunction with this, OCR (Optical Character Recognition) software capable of reading commonly used fonts and in some cases 'learning' new fonts. Now that automatic text input (at least of 'standard office fonts') is so widespread, there will be more demand for acquisition, using the same equipment, of information contained in various other forms of binary image - circuit diagrams, for example, as well as music. Currently, these can be acquired in bit-map form, but the recognition of the constituent symbols is the subject of on-going research. The following sections provide background information regarding pattern recognition of binary images of various types, concluding with a review of previous work on automatic reading of music scores.

3.2 PATTERN RECOGNITION OF BINARY IMAGES

The largest area of research within the field of pattern recognition of binary images is Optical Character Recognition, i.e. automatic reading of text. Software is now commercially available, either incorporated into a scanning device or as a separate product, which will read high-quality material containing

text in a limited range of fonts and point sizes (e.g. ReadRight [1988]). Additional limitations include restrictions on skewing of the original and the type of printing device used in producing the original. Normally, the technique behind software in the lower end of the market is template matching, where the character under test is compared exhaustively with a set of bit-map images of characters in the system's library. The character with the highest correspondence measure is output. Contrary to this, most research papers deal with structural or feature-based methods; however, recently released OCR systems, particularly the more expensive ones, are implementations of such techniques [Discover 1988].

Pixel-based thinning is a commonly-used method for initial data reduction and, possibly, feature extraction, producing a 'skeleton' of the original image by stripping off boundary pixels. This is a time-consuming process (attempts have been made to improve performance, for example by implementation in hardware or parallelising) which may remove structurally significant portions of the image such as short protrusions, or introduce extraneous limbs or 'hairs'. These faults have to be considered when designing the later stages of a recognition system, leading perhaps to the inclusion of a post-processing stage to remove hairs [Harris *et al.* 1982]. Once the skeletonising operation is complete, the original image will have been converted into a connected list of nodes (or 'branching points') and segments (or 'strokes') which will then be passed on to the recognition stage for identification of 'features' - arcs, lines, holes, etc [Pavlidis 1983].

Alternative methods for thinning or vectorisation have been suggested, including using the polygonal approximation to the contours of an image [Meynieux *et al.* 1986] or using the line-adjacency graph (LAG) of an image [Pavlidis 1982]. Those methods aimed at processing just line-work can be separated from those intended to produce, in addition, a structural description of regions and miscellaneous filled shapes. Work directed towards reading general office documents needs to take this capability one stage further. This would entail the distinction of grey-level or colour regions from binary graphics and then further division of the latter into text - to be forwarded to an OCR module - and graphics - to be vectorised or processed by a recognition module appropriate to the type of image involved [Maynieux *et al.* 1986, OmniPage 1988].

Obviously a recognition system for printed music must be able to describe blobs (e.g. filled noteheads) as well as line-work (barlines, stavelines, etc.). After approximating the contours of an image with polygons, Maynieux *et al.* [1986] matched pairs of segments from this outline which were below a threshold for spacing (i.e. the maximum line thickness), and roughly parallel, in order to find lines. Segments which could not be paired in this way had, therefore, to delimit non-linear regions. Much use has been made of the LAG (and transformed LAG) as a basis for thinning or feature extraction. Applications include reading English text [Grimsdale *et al.* 1959, Hättich *et al.* 1978, Duerr *et al.* 1980, Pavlidis 1986, Kahan 1987] and Chinese characters [Badie 1985], analysing electrical circuit diagrams [Bley 1984] and counting asbestos fibres [Pavlidis 1978]. This is also the basis of the

music recognition system described in chapter 4. The LAG is derived from a run-length encoded version of the image. Nodes of the graph are formed by continuous runs of black pixels and branches link nodes which are in adjacent columns and which overlap. The graph can then be used directly in a similar way to a skeleton, or various rules can be applied to the nodes and branches, agglomerating or removing these to produce a transformed LAG. More details of the latter technique are given in chapter 4.

The use of context is another variable in the text recognition process. Wolberg [1986], for example, did not make use of context, so that a 'superior' system could be produced when contextual information was supplied. On the other hand, Hull and Srihari [1986] used context at the word level in a procedure termed 'hypothesis generation'. For each word a set of extracted features were used to select a subset of words from a given vocabulary. This subset should have contained a correct match for the original word. A 'hypothesis testing' stage - implemented as a tree search - discriminated between the words in the subset using 'inner features' i.e. features located (spatially) between those used in the hypothesis generation stage.

In general, pattern classification is achieved using either a statistical or structural approach [Baird 1986]. In an effort to benefit from the advantages of both these methods whilst avoiding their disadvantages, some researchers have made use of composite approaches. Duerr *et al.* [1980, Hättich *et al.* 1978] used a hierarchical approach consisting of four stages, the first statistical, followed by two structural (the first of these making

use of a transformed LAG, as mentioned previously) and the 'mixed' last stage made the final classification in conjunction with results from the earlier stages. The reasoning here was that patterns exhibit both 'characteristic structures' and 'probabilistic deformations'. Pavlidis [1983] used a different form of combined approach. A structural technique was used for character decomposition in order to cope with wide variations in the input, but the results of this were not passed to a syntactical analyser as might be have been expected; instead a binary feature vector-based statistical classifier was used. This was because the large number of classes involved in an OCR system designed to cope with a variety of fonts and sizes (in addition to Greek characters, mathematical and technical symbols, and 'possibly hand printing') rendered the former approach impractical.

The recognition of Chinese and/or Japanese characters is a different form of text recognition, with its own variety of approaches. As referenced previously, Badie and Shimura [1985] used a transformed line adjacency graph, in their case to extract line segments from handprinted Chinese characters. They cited the problems with hairs and various distortions of conventional pixel-based thinning as their reason for using a LAG-based approach, and relied on a set of heuristics to perform the final classification of line segments. In the work of Tsukumo and Asai [1986], which dealt with machine-printed Chinese and Japanese characters, numerous horizontal and vertical scanning lines were used and features built up from the number of strokes crossed by these lines. In contrast to these stroke-orientated approaches,

Feng and Pavlidis [1975] decomposed the polygonal approximation to the boundary of each character into simpler shapes - convex polygons, 't' shapes and spirals. They proposed that recognition could then be achieved either by producing feature vectors derived from the characteristics (or simply presence or absence) of certain shapes or by using a graph structure processing scheme. Interestingly, results were also given for processing chromosomes, in addition to Chinese characters, showing the method to be equally applicable.

The recognition of mathematical formulae is another form of text recognition. In addition to the standard alphabetic characters, symbols such as '+', '-', '*', '/' and parentheses are used, as are various point sizes (for example integral or summation signs in appropriate circumstances). Recognition of mathematical formulae is a 2-D problem, a characteristic it shares with automatic reading of music scores, unlike ordinary OCR of text strings which is commonly 1-D (see Byrd 1984, section 2.4, for a comparison between the complexity of mathematical formulae, Chinese documents and music notation). In the work of Belaid and Haton [1984] a syntactic approach to this problem was used, whereby a high priority operator in the formula under examination was chosen as a starting point, and its operands were then broken down iteratively until terminal symbols were reached. A list of rules defining the grammar of a subset of possible formulae was used in this analysis. Although this work used input from a graphics tablet, the above approach could equally be applied to an image-based system.

Engineering drawings of both mechanical and electrical varieties have been the subject of a significant amount of pattern recognition research [Pferd 1978, Clement 1981, Bunke 1982, Bley 1984, Okazaki 1988]. Clement [1981] used a low resolution scan to find line-work, rather than using the full resolution of the scanner over the entire image area, given that a large proportion of this would commonly be background. It was then proposed that remaining portions of the drawing would be scanned at full resolution in order to achieve raster-to-vector conversion of more complex structures and, where appropriate, character recognition. Pferd and Ramachandran [1978] reviewed scanning and vectorisation techniques and described their LAG-based algorithm for converting run-length encoded images of engineering drawings into vectors. They saw the conversion of the vector representation into a CAD database as 'desirable' but not 'essential' given that significant data compression had been achieved and editing (of the vector list) enabled.

Bley [1984] used a transformed LAG in order to segment circuit diagrams. The resulting graph was split into 'large' and 'small' components, the former consisting of line-work and large symbols, and the latter the legends, i.e. text contained in the diagram. Small components were clustered, forming associated characters into words ready for passing on to an OCR stage. After 'dominant line elements' had been extracted, the remaining large components were processed using 53 'production rules' which analysed and modified the transformed LAG in order to produce the final vectorisation. Bunke [1982] introduced the attributed, programmed graph grammar as a means of interpreting previously

vectorised circuit diagrams and also flowcharts. A graph representing the input diagram was processed using a set of 'productions'. These transformed the graph, either performing error correction of the input, for example, removing extraneous short line segments, bridging gaps in lines, etc., or producing the output representation for a particular symbol. These transformations made use of attributes of the nodes and edges in the original graph (spatial relationships, line lengths, etc.) together with 'applicability predicates', which specified constraints on the attributes, and were in turn 'programmed' by a 'control diagram' which determined the order of application of the productions.

In a recent paper, Okazaki *et al.* [1988] used a loop-structure-based recognition process in reading circuit diagrams. Nearly all logic circuit symbols contain at least one loop, i.e. a region of background completely surrounded by line-work. A few do not: resistors and earth for example, and these were dealt with separately. Loops were detected in the original diagram and, for each loop, an appropriate bounding window (termed a 'minimum region for analysis' or MRA) was determined within which testing could take place in order to achieve recognition. A hybrid method was used for this, combining template matching of primitives, \square and \circ for example, and feature extraction, using the number of connecting lines, the number and size of holes, etc. Production rules were used to mediate between the sets of results derived from the two approaches. These divided into inference rules, where a candidate result was obtained despite the above processes producing different results, and test

rules, where a recognition result was checked for various parameters before being output. Symbols which did not contain loops were recognised by line tracing from end and corner points, and matching structural features (branch, corner and end points) using a graph structure representation. In addition to reading symbols with and without loops, line-work and rectangles (macro gates), the system read text which was defined as consisting of freehand characters in the OCR font.

Recognition of hand-drawn diagrams has also been widely researched. Sato and Tojo [1982] used line-tracking as the basis for a system which interpreted freely-drawn circuit diagrams and flowcharts. Initially, by using a coarse scan, the average line width and minimum line spacing were determined. Then, using these measurements, a tracking window was set up, which was used in the line-following process. If black pixels were found at the edge of the window during line-following, the region in question was termed 'complex' and was saved on a stack for later, detailed, analysis. Complex regions included bends, branches, crossings, arrow marks (in flowcharts) and dots. After line-following was complete, arcs and straight line segments were distinguished. Relations between detected primitives (lines, arcs, circles and dots) could then be analysed and symbols recognised according to a *priori* knowledge of the structure of permitted symbols.

Suen and Radhakrishnan [1976] concentrated on reading hand-drawn flowcharts consisting of boxes constructed from straight lines, interconnecting line-work and associated arrows. Following initial thinning, a run-length encoding-based method was

used, in this case for horizontal line detection. Line tracking was then undertaken from the ends of each horizontal line, and the direction of these new lines was quantized into one of six possible directions. This was sufficient to distinguish all but two categories of symbol (which required one extra test) while the diamond-shaped symbol was treated separately as it does not contain a horizontal line. The interconnecting lines could then be traced and associated directions determined using *a priori* knowledge of the number of permitted connections to a particular type of symbol and recognition of the requisite arrows. This information was then output in tabular form and it was proposed that, with the addition of a character recognition capability, a flowchart alone could be used for program input.

Furuta *et al.* [1984] also made use of run-length encoding, but in processing hand-drawn piping and instrument diagrams. Once a portion of line-work was detected (a group of runs which were below the threshold for maximum line thickness and which did not form an arc or bending point), line tracking commenced. When either the line thickness increased suddenly or exceeded the line thickness threshold, a bending point was encountered, or no continuation of the line could be found after traversing a break, a symbol was deemed to exist. Geometrical feature points were used in order to achieve symbol recognition. These included end, corner and branch points, filled regions and isolated points. Noise removal and line extraction were also performed and then feature vectors built up, using the number of occurrences of each type of geometrical feature point, the number of lines, etc. A measure of similarity between the vector under test and that of each

'standard symbol' was calculated and used in conjunction with a threshold in order to complete the recognition process.

3.3 PREVIOUS WORK ON PATTERN RECOGNITION OF PRINTED MUSIC

In the field of pattern recognition of printed music, the earliest recorded work is that of Pruslin [1967] at M.I.T.. This work was followed up by, and to a limited extent continued by, Prerau in the late 1960s and early 1970s [Prerau 1970, 1971, 1975]. A third worker at M.I.T., Mahoney [1982], pursued work in the same area more recently, as part of an undergraduate project.

Further research on this subject has been undertaken by Japanese workers. Matsushima *et al.* [1985a, 1985b, 1985c] produced the vision system for the WABOT-2 keyboard-playing robot and have subsequently integrated a braille score production facility into their system [Hewlett 1987, 1988]. Nakamura *et al.* [1979] developed a score-reading facility as a means of acquiring data which could then be used in forming a database for use in work aimed at analysing Japanese folk-songs. Aoyama and Tojo [1982, Tojo and Aoyama 1982] also developed a score-reading system as a means of entering information contained in existing sheet music into a database.

Other research work in this area, although apparently of a short term nature, has also been reported by Wittlich *et al.* [1974], Andronico and Ciampa [1982], Tonnesland [1986], Martin [1987] and Roach and Tatem [1988].

Work along similar lines by Gary Nelson and Terry Penney [Nelson 1973b], i.e., 'translating films of printed or handwritten music into numeric data suitable for analysis by computer,' has not been reported in detail.

Two publications by Michael Kassler [1970a, 1972] concerned automatic recognition of printed music. The first of these, 'An Essay Toward the Specification of a Music Reading Machine', went some way towards laying out what the machine should be able to recognize and included an original representational language. The second, 'Optical Character-recognition of Printed music: a Review of Two Dissertations', discussed the work of Pruslin and Prerau. A summary and discussion of Pruslin's work appeared in 'Recognizing Patterns' [Eden 1968] which put the music recognition problem in the context of other pattern recognition work.

The following paragraphs discuss the above work in more detail.

3.3.1 Background

The aims of researchers mentioned above ranged from forming a database (Aoyama and Tojo, Nakamura *et al.*) to providing a robot vision system (Matsushima *et al.*). The work of Pruslin and Prerau was intended to achieve limited symbol recognition in order to enable general applications. In contrast, Mahoney and Roach and Tatem concentrated on the problem at a lower level, recognising symbol components. A significant proportion of the effort of Pruslin and Prerau was targeted, however, on the specific aspects

of note-cluster detection and staveline extraction respectively.

All three M.I.T. authors mentioned the distinction between musical symbols which can be treated as characters (because they are the same on each appearance) and those which have varying graphical parameters, such as slurs. Pruslin treated notehead clusters as characters, but beaming complexes as varying combinations of parallelograms. Prerau gave special attention to the problems of recognising non-character symbols whilst Mahoney's approach of detecting primitives, rather than complete symbols, partially solved this problem.

A question of terminology arises when comparing the aforementioned works. Prerau coined the term 'sofon' (Sharp Or Flat Or Natural) to describe the sharp, flat or natural sign in any context, as opposed to using the term 'accidental' which, strictly, implies an alteration of the pitch of a note, compared to either its previous occurrence or the current key signature. In this thesis the term accidental will be used in the strict sense of the word, to refer to one of :- sharp, double sharp, flat, double flat or natural.

3.3.2 Aims

The aims of the aforementioned researchers varied widely. Prerau aimed to produce a program which could be expanded easily given that his work could not be comprehensive, while Mahoney emphasised design, thus presenting the basis for a 'real' system. He advocated retaining as much textual information as possible so

as not to favour a particular representation scheme, and measured the usefulness of a music recognition system by its flexibility (ability to cope with variations in style and print quality). An important point which Mahoney mentioned in outlining his research philosophy, which will recur in chapter 4, is the trade-off which exists between robustness and simplicity of the recognition task.

Nakamura *et al.* aimed to produce a database of Japanese folksongs in order to study and manipulate these, as sound and printed score, using a computer. Aoyama and Tojo also aimed to produce a database, but of more general material, and as part of an interactive music editing and arranging system. In contrast, Roach and Tatem's work was prompted by the economics of music publishing, where a large amount of money is spent on converting composers' manuscripts into engraved notation.

3.3.3 Acquisition (scope of input material, scanning and thresholding)

The scope of the input material also varied. Pruslin asserted that complete recognition was achieved when the type, order, volume, tempo and interpretation of notes were specified, but his work only attempted to recognise solid noteheads and beaming complexes, as well as determining note order, in single bars of piano music.

Prerau used a flying-spot scanner to digitise samples consisting of two or three bars of a duet for wind instruments taken from Mozart K.487. The scope of his work was defined as an

engraved sample of standard notation, where this was taken as 'most instrumental and vocal music between the end of the 17th century and the beginning of the 20th century'. Recognition was limited to that notation which needed to be recognised in order to enable a performance of a minimal version of the score. That was, notes of all types, rests, clefs, time signatures, key signatures accidentals, and dots, but not dynamics, tempo markings, ornaments, etc. The source material was chosen to contain all basic notational symbols while being relatively simple. Duets were chosen because they provided structural features of larger ensembles whilst using single-note-per-voice notation. The latter requirement was stipulated, ostensibly, to lessen the overlap with Pruslin. The point was emphasised that the source music (K. 487) was from an ordinary book, i.e. not specially prepared for computer input. The samples used were 1 1/2" x 1 1/2", i.e. two to three bars of the duet music digitised at a resolution of 512 x 512 pixels over the total image area of 2 1/4" x 2 1/4", giving approximately 225 d.p.i.. These were grey-scale images and the threshold was chosen 'by eye' to give staveline thickness of approximately three pixels, given that 'any thinner line would run the risk of having breaks in stavelines. Since staff-line continuity is an important property used in the isolation section, staff-line breaks are to be avoided.' Unfortunately, staveline continuity cannot be relied upon, as will be seen in chapters 4 and 5.

Andronico and Ciampa also used a flying-spot scanner, with negatives of 24mm x 36mm at 512 x 512 resolution with 64 grey levels. Binarisation was achieved using a manually selected

threshold, although the use of automatic thresholding was a future aim.

Mahoney mentioned that the highest possible resolution, although desirable, was likely to produce prohibitively large images. Also, he used no preprocessing in order to reduce the effects of noise, because the greatest difficulties were 'usually inherent in the printed text itself'. The worst case of this is perhaps provided by the breaking up of a symbol which needs to be connected for recognition purposes. This subject is discussed further in chapter 5. Mahoney hoped that enough leeway was inherent in his method to 'absorb flaws', although he added that touching-up by hand was a possible solution. He provided a detailed analysis of the processing of an extract of two bars of guitar music. Resolution of 100 microns (254 d.p.i.) was used to produce a 256-level grey-scale image. This was then thresholded by setting all pixels with value greater than zero equal to one.

The WABOT-2 vision system (the work of Matsushima *et al.*) required real-time recognition using images from a video camera, sometimes derived from distorted music sheets. Single A4 pages of electronic organ score containing relatively simple notation using three stave systems provided the source material. The method of image acquisition led to variations in the image due to position and characteristics of the light source, camera tilt and resolution, in addition to distortions of the sheet of music and inconsistencies in the notation itself. The CCD camera produced images of 2,000 x 3,000 pixels with 256 grey levels in approximately two seconds, with the score situated about one metre

from the camera. The image was subdivided and each region separately thresholded to allow for uneven illumination. The image was then rotated as required and normalised to compensate for distortions introduced at the scanning stage.

The scope of Aoyama and Tojo's system covered single melody lines and more complex scores incorporating multiple voices. The size of the music was free within certain limits and, to some extent, distortion, blurring and breaks in stavelines were permitted. A drum scanner with the same specification as that of Mahoney (i.e. 254 d.p.i. resolution and 256 grey levels) was used, enabling entry of a complete page, whilst avoiding the problems encountered by Matsushima *et al.* in using a video camera. Two scans were used; the first provided several blocks of widely spaced scan lines which were used in determining the binarisation threshold and staveline location, while the second was the complete high resolution scan. The page was, however, broken up into windows for processing. This is contrary to the structure of a large amount of music and is a major limitation when processing multi-stave systems and symbols which straddle two staves or fall on a window boundary. Each of the windows contained a single stave and was stored in run length encoded form - an approach used by Wittlich *et al.*

Nakamura *et al.* dealt with monophonic music in the form of Japanese folk-songs. The vocabulary of symbols covered included notes, rests and accidentals. A CCD-array-based scanner was used for image acquisition and some smoothing of the image was attempted as part of the binarisation procedure.

Roach and Tatem worked with a full page greyscale image at 1200 x 800 pixels (equivalent to 100 d.p.i.), and some smaller images containing a limited range of symbols, and aimed to extract pitch and duration information.

Wittlich *et al.* also used a flying-spot scanner, in their case to produce a single image (1200 vertical x 1000 horizontal pixels) of a page of Debussy piano music.

3.3.4 Staveline location and segmentation

Finding the stavelines in an image is a prerequisite of recognition of conventional music notation. It is also a non-trivial task, a point emphasised by several workers. Prerau pointed out that segmentation of individual symbols was more complicated for music than for character recognition. Only occasionally do letters have to be separated in OCR, when the text in an image is of poor quality. In his work, 'about as much effort went into isolating the symbols as went into recognising the isolated symbols.' Also, on the same subject, he drew attention to the important fact that 'the original five stavelines are generally not exactly parallel, horizontal, equidistant, of constant thickness, or even straight.' Pruslin simply removed thin horizontal lines by thresholding the length of continuous vertical runs of pixels, assuming that a figure for 'line thickness' was known. This approach prevented Prerau from achieving his intended aim of expanding Pruslin's work, because it distorted symbols and prevented their recognition. Both Pruslin and Prerau used contour

tracing, the latter in his own method for separating symbols from the stavelines, termed 'fragmentation and assemblage'. This involved a contour trace proceeding along each edge of each staveline in turn and when the gradient exceeded 1:10, a 'deviation point' - the start of a fragment - was deemed to exist. A 'staff-line border' was then set up. This was a horizontal line, starting from the deviation point, which formed the edge of the fragment where, originally, it touched the staveline. The contour of the complete fragment could then be found. Fragments were given type numbers according to the number and position of the stavelines (if any) to which they were connected. Fragments which did not touch a staveline had to be found using a separate, somewhat laborious process involving finely-spaced search lines which spanned the page. The fragments were then assembled using a criterion which assumed horizontal overlap, so as to reconstitute the symbols but without the stavelines present in the original. Unfortunately, this criterion is not always satisfied, for example, where a symbol such as a shallow slur or bass clef coincides with a staveline, it may be fragmented.

Instead of using the approach taken by Prerau, i.e. removing the stavelines and then restoring those parts which coincided with symbols, Andronico and Ciampa devised a technique which aimed to remove just the exposed stavelines. No details of the staveline recognition method were given, although it was mentioned that 'successive trials' were used in searching for the stavelines and that the number of iterations required was proportional to the amount of background noise.

The isolation of symbols from stavelines was an important objective of Mahoney's work. He singled out lines, both straight and curved, as predominating in common music notation. Also, he stated that lines could be described by their run-length encoding in conjunction with collinearity and proximity constraints for dealing with gaps. Line extraction was described as 'easy' given the above line encoding, but details of the process used were not given. Regions which were not lines were found as 4-connected components by flood-filling [Duda 1973]. With regard to staveline processing, Mahoney mentioned permissible gaps in lines, where symbols were superimposed, and suggested interpolation between end-points. Similarly, close ledger-lines from adjacent notes may have been treated as a single line by his method, but apparently harmlessly. Other problematic configurations which Mahoney mentioned included two open noteheads either side of a staveline, the F-clef and time signatures, all of which are examples of situations where portions of symbols coincide completely with stavelines. The minims (or semibreves) could be detected, he asserted, by locating the internal white dots, but this presupposes that the black boundary is closed. Replacing short lines after staveline removal was a suggested partial solution for the other two cases, involving the F-clef and time signatures. If a stave or ledger-line passed through a hollow notehead, the above technique could still have been used, once the portion of line within the notehead had been removed. Another situation which was mentioned concerned a note stem in a crotchet chord which would have been treated as ending where it met a close cluster of noteheads. The association of all the noteheads with the stem would have to be achieved nonetheless. Similarly, where the tail

of an individual quaver touched its notehead, the separate components (notehead, stem and tail) would still have to be isolated. Passing reference was made to the difficulties which arise when beams and stavelines are coincident for any significant distance, thereby disrupting association of staveline segments. A general rider was provided to the effect that 'these situations are not generally handled by the system presented in this thesis.'

The stavelines in the scores processed by the system of Matsushima *et al.* were detected by a short bar-like filter which operated down equi-spaced columns in the image, simultaneously with the scanning process. Pulsed output from the filter indicated the presence of stavelines. (Similarly, Wittlich *et al.* used a bar-like filter which was available as a function of their scanner.) The points where the presence of stavelines was indicated were joined to form straight lines, and where five equi-spaced lines were found, a stave was deemed to exist. Staveline inclination and curvature, and failed detection all forced a need for flexibility, and similarly, long slurs parallel to the stavelines had to be eliminated by checking vertical spacing.

As already mentioned, Aoyama and Tojo used two scans. The stavelines were found by forming the horizontal histogram of black pixels within each block of low resolution scan lines, and using a threshold to find sets of five peaks. The staveline fragments were then pieced together, line spacings established and line spacings calculated. Coarse segmentation was then undertaken, removing obvious, exposed sections of (stave-)line-work by examining the

vertical run-lengths involved, but leaving short portions of staveline where these existed in the proximity of a symbol. This was intended to help avoid breaking up minims and the like where they coincided with the stavelines, as the fine segmentation process could examine each symbol or connected symbols more carefully. Both black and white noteheads were detected as part of fine segmentation - by searching for sequences of overlapping vertical runs of pixels - in order to assist in correctly removing remaining staveline fragments.

Roach and Tatem described staveline finding as 'a particularly difficult problem'. They implemented an existing line-tracking algorithm which calculated line direction and thickness at each pixel in a grey-scale image by passing a window of appropriate proportions over the image. They pointed out that, where a symbol coincided with a staveline, the pixels involved 'belonged' to both, and so stavelines needed to be 'intelligently removed'. The least-squares fit through lines was found and stavelines were identified as horizontal lines stretching across almost the width of the page. Vertical lines were found in a similar way to horizontal lines and then a circularity measure was applied where a 'wide' portion existed at the end of one of these. This was classified as a notehead if its circularity exceeded a threshold. Thinning was used on isolated components to produce chain codes. These were segmented at junction points and arcs with high curvature were subdivided ready for use by the recognition routines. Flood-filling the background (i.e. white pixels) was used to locate 'holes' (small white areas contained within symbols).

Nakamura *et al* used manual entry of the starting co-ordinates for a line-tracker which constructed least-squares fit lines for each of the stavelines. Then, as with Wittlich *et al* and Pruslin, a threshold for line thickness was used to erase the stavelines and achieve segmentation.

The use of a bar-like filter (Wittlich/Matsushima *et al*) is not only vulnerable to staveline inclination and curvature, but also to the effects of multiple beams or other linear elements which can be present in a score. Also, short staves containing realised ornaments, for example, would not be detected. The same applies to the use of a horizontal histogram of black pixels, even locally (Aoyama and Tojo). All these aspects are covered in chapters 4 and 5.

3.3.5 Grammar and syntax

Prerau provided syntactic rules for a limited subset of music notation as well as mentioning the higher-level grammars which are present in music notation but which were not covered by his thesis. He made use of syntax and redundancies, for example flats could only appear in one of two positions (this excluded those special cases not within the scope of Prerau's work) - in a key signature to the right of a clef or barline, or as an accidental. Also, the clef was the only symbol which could be first in a line of music. Redundancy in music notation was exemplified by the first flat of a key signature having to be on the middle line (assuming treble clef), or conversely, if the first symbol of a

key signature was on the middle line it had to be a flat. Similarly, Prerau asserted, if the first symbol of a key signature was a flat, then the second symbol in the key signature (if any) had to be on the top space and a flat. Prerau also limited rests to certain vertical positions and supplied constraints for other symbols. Time signatures had to be to the right of a clef, barline or key signature, the triplet indicating numeral '3' had to be overlapped by a beamed group of three notes and dots had to be positioned appropriately for duration augmentation or as part of a repeat sign or F-clef (staccato and other dots were not permitted).

Andronico and Ciampa formulated two generative grammars. The higher order structures of music down to the individual symbols were represented by one grammar and the components of the symbols by the other. Examples of components are vertical lines of various lengths, white and black dots, etc. Similarly, Matsushima *et al* made use of a simple hierarchical structure for music notation in directing the correlation techniques used for detecting symbols and symbol components. Stavelines, noteheads and barlines, which could occur anywhere over a large area were searched for using hardware-implemented correlation, while other symbols (clefs, rests etc.) were found using software-implemented localised search techniques. The use of a mask to detect crotchet noteheads led to numerous spurious matches which had to be filtered out at a later stage. This problem would inevitably worsen in the case of more complex notation and this shows the weakness of the approach, given that the speed factor is overcome by implementation in hardware. Only treble and bass clefs were permitted in their work,

and these only at the beginning of a line. Musical syntax rules used in error-detection and correction included the following :- the playing times for each part had to be equal, a clef and a key signature had to begin the opening bar of a part, and, similarly, a time signature had to exist in the first bar of a score.

Aoyama and Tojo used the following syntax rules :- a key signature was only permitted on the right hand side of a clef, the first sharp in a key signature had to be on the fifth line (treble clef), and accidentals had to be on the lefthand side of a note-head. They also compared the sum of the rhythm values of the notes in each bar with the time signature and any discrepancies were used in the error correction procedure. This ignores the problems of n-tuplets where, upon multiple repetition, the associated numeral is omitted, and also mathematically-incorrect beamed groups in cadenza passages. Nakamura *et al* drew attention to the lack of rigid rules for writing music notation and said that rules used in practice are often based on 'customary usage'. As a result of this, they concluded that it was impossible to check recognition results by using musical grammar and instead relied on man-machine interaction (using the sound and print production facilities of their system) for error-correction.

3.3.6 Object (symbol) formation and recognition

Contour tracing after horizontal and vertical line removal provided the components and their parameters (relative and absolute size and position) for processing in Pruslin's work. As mentioned previously, note cluster detection required a large

proportion of Pruslin's effort. Twenty-three possible arrangements of notehead clusters made up from less than five noteheads were tabulated and used as the basis for the processing of crotchet chords. This attempt to treat chords as 'character' symbols is severely restricting in view of the prohibitive number of 'models' which would be required for a practical system. The identification process categorised the permutations of noteheads using height and width information. Those clusters with width greater than a single notehead had their contour trace examined in specific columns and the number of black/white transitions determined. The number and position of these crossing points was used in order to achieve classification.

Beaming complexes were characterised as combinations of parallelograms with appropriate restrictions on spacing and extent of subsidiary beams. It was explained that, due to intersecting notestems or stavelines, scanner resolution and/or poor print quality, the constituent parallelograms of a beaming complex may or may not have formed a single contour trace. The principal beam, or 'timing bar base' (in this case the beam on the opposite side of the beaming complex to the notestems) was treated separately, and subsidiary beams were related to it, and the positions of the characteristic transitions in thickness extracted. These 'jumps' were detected by setting a threshold for change in thickness at just less than half the staveline spacing and using this in conjunction with a parameter for permitted horizontal deviation within the thickness transition. Parallelograms (subsidiary beams) which became separated from the main beam as a result of pre-processing were subsequently detected and merged using a

threshold for permitted vertical spacing. The beaming complex was classified according to whether subsidiary beams were present, and if so, on which side of the principal beam. Finally the slope of the principal beam was calculated.

Operations were subsequently performed with the aim of ordering notes and determining their rhythm values. Ambiguities regarding regions which could still be either note clusters or beaming components were resolved using the fact that the latter had to have related note clusters at both ends. Information regarding the permitted stem direction for each form of note cluster was also used. Pruslin also made use of short horizontal scans on the original image in order to determine whether stems associated with a quaver (i.e. single) beam were above or below, as beam and noteheads alike were 'floating' in free space following the pre-processing. Where note clusters could be attached to either an ascending or descending stem, similar searches were made. The problem of ordering the detected notes was discussed and the unsuitability of simple left to right ordering was analysed. The vertical alignment across staves of note clusters was examined, and the corresponding sequence (timing) information was extracted.

Prerau used the normalised bounding rectangle (normalised relative to the stave space height) to produce lists of possibilities for each symbol, after making the assumption that, unlike alphabetic characters, each musical symbol differed in size from most others. The tests he used which were based on syntax, position and redundancy have been mentioned in section 3.3.5. When

these tests failed to remove ambiguities, another type of test was used which involved measuring features. Feature tests were used to distinguish between sharp, flat and natural signs and between the different types of non-beamed notes. An example of such a test involved measuring the width of a symbol at its vertical mid-point, thereby distinguishing a stem-up quaver from a crotchet. Sharp, flat and natural signs were distinguished by finding the horizontal position of the top and bottom-most points of the symbol relative to its bounding rectangle. The procedure for determining the pitch of a note on the staff was not described. Noteheads in a beamed group were found as single-connected fragments, whilst corners of beams that also formed single-connected fragments were detected and removed. Barlines and double barlines were differentiated as follows :- if a barline had at least one hole it was considered double and the staff space where this occurred was tested to ascertain the appropriate combination of thick and thin lines. Hollow and solid noteheads were distinguished by a contour trace which detected the presence of an inner boundary in the former. The pitch of notes on ledger lines was determined by counting the short protrusions on the opposite side of the note stem to the notehead. This is particularly unreliable in practice, as these may not exist (see, for example, figure 5.7). In the case of the note stem being downwards, if the distance from the topmost protrusion to the top of the notehead was greater than $\frac{3}{4}$ of the staff space height, the notehead was above the ledger line, otherwise it was on the line. An equivalent procedure was adopted in the case of an up-stem.

A specific test found the beams of each beamed group. The thickness of the beam component was found at points spaced at intervals of $1/5$ of the distance between note stems. These thicknesses were used as follows :- the larger of the first two gave the thickness for the left-hand note and similarly for the second pair and the right-hand note. A thickness up to the stave space height corresponded to a single beam, one to two times this measure equalled two beams, and so on. Unfortunately, where localised measurements such as these are used, noise can severely distort the results.

Andronico and Ciampa's program recognised clefs (of five types), key signatures (using flats or sharps), accidentals and a subset of notes and rests. The brief description of the symbol processing implied that specific points were examined. These were located on the stave/ledger lines and on the mid-points between these lines, in each column of the image. The length of any vertical line segment present at a point was measured and a crude deduction drawn, for example a 'long' line indicated a note with a lefthand stem. The horizontal and vertical position of each symbol was recorded in addition to symbol type and rhythm value, as appropriate. The authors mentioned lack of good results in processing notation half the size of that used for the examples in their paper, but proposed, as a solution, scaling by software-control of the camera which was to be used in future work.

In contrast to the above, the objective of Mahoney's work was to cope with symbol primitives, thus providing the basis for

recognising composite music symbols in terms of these primitives. For complex symbols (sharp/flat/natural signs, clefs, etc.), which could not be broken down naturally into the above primitives, correct isolation was the sole aim. The work concentrated on extracting the primitives, not on combining them into complete musical symbols. The 2-D relationships between symbols were expressed using proximity and relative position predicates, the former used normalised distance while the latter used left, right, above and below. The measurements used for normalisation were the thickness of the stavelines and the stave space height. Histogramming the lengths of both black and white vertical lines was used to find the normalisation measure; thus, the most common black line length gave the staveline thickness and the most common white line length gave the stave space height. No mention is made however, of different size staves occurring simultaneously in one image. Areas were apparently normalised using the area of the interior of a semibreve, an unreliable measurement given the variability found in this feature in practice.

The parameter list for lines and symbols which Mahoney proposed provides several points of interest and illustrates some drastic limitations of the system. For example, the upper limit for the length of a beam was set at 20 x the stave space height, while the length of a barline was limited to 7 x the stave space height and the permitted angle of rotation for horizontal and vertical lines was $\pm 10^\circ$. Beams could be within $\pm 45^\circ$ of the horizontal, but with no extra allowance for rotation of the image. Also, notestems were distinguished from barlines by using length, so that a vertical line up to 4.5 x the stave space height was a

notestem, and above that it was categorised as a barline. A barline was, however, permitted a thickness up to 50% greater than a notestem. After removal of all lines, both vertical and horizontal, individual solid noteheads were detected as isolated regions of the appropriate size. Vertical clusters (chords) of solid noteheads were dealt with by separating out the individual dots by erasing the 'ideal' stave (which consisted of continuous stavelines formed by interpolating between the broken lines extracted from the image) and ledger lines. The individual noteheads could then be recognised, although, as is mentioned, a lower area threshold would be required. A tail and a sharp were also extracted from the test image, as these were the only other types of symbols dealt with by the work.

The correlation techniques used in conjunction with threshold measurements by Matsushima *et al.* for detecting noteheads, barlines etc., were described in section 3.3.5.. Clefs (treble and bass) were discriminated by the crude technique of measuring in from the start of the stave in two of the stave spaces and comparing these distances. Similarly, time signatures were distinguished by localised measurements effected along the centre-lines of spaces. As mentioned previously, such localised measurements are highly vulnerable to the effects of noise. Accidentals were located by searching to the left of noteheads for vertical lines, and the relative lengths of these lines were used in determining which symbol (sharp, flat or natural) was present. The region surrounding each notehead was checked for the presence of tails, rhythmic dots, and tenuto and staccato marks. Beams were treated by counting the number of vertical black runs in a pair of columns

equi-spaced either side of the note stem under test.

Aoyama and Tojo achieved recognition using two stages termed coarse and fine segmentation. Initially, the symbols were divided into 10 groups using a normalised feature space (normalised relative to the stave space height) similar to that used by Prerau. Separate treatment was then applied to each category in order to achieve recognition. For example, the symbols with the largest bounding rectangles - slurs and beamed groups in this case - were separated by searching for the presence of a vertical component of suitable length (a note stem). The positional relations between noteheads and stems were classified into 10 types, along the lines of Pruslin's technique for dealing with chords mentioned at the beginning of this section, although encompassing polyphonic music where the noteheads of separate parts touched. The latter were separated and then treated individually. As a further example of fine classification, the crotchet rest, quaver rest and sharp, flat and natural signs were divided by a dedicated algorithm. This made use of the effects of erasing portions of these symbols using four preset threshold parameters relating to the width and height of constituent runs of black pixels. The authors drew attention to compound symbols - i.e. those made up of several separate components, the F-clef for example. By examining their relative positions, the different dots involved in the F-clef, the fermata sign, the repeat barline, duration augmentation and staccato could, the authors asserted, be distinguished.

Nakamura *et al.* reasoned that although musical notes are

simpler patterns than alphabetic characters, related positional information is more important. Their recognition technique involved extracting characteristics and position information from X and Y projection profiles of the symbols after staveline erasure. Projection parameters used included the number and position of peaks, the width of the upper and lower halves of the symbol and the number of 'protrusions' (the 'limbs' extending from the main stem of quaver - and shorter duration - rests and also the tails on single quavers and shorter rhythm values). The position of any notehead present was also extracted.

Roach and Tatem listed some of the problems regarding recognition, particularly of handwritten scores (none of the other authors attempted automatic recognition of *handwritten* music). Examples were noteheads not closed, stems not attached to noteheads, beams which resembled slurs and ended well away from their associated stems and symbols such as crotchet rests appearing in multiple guises. They argued that even people had difficulty reading some handwritten scores, especially if they did not have the musical knowledge necessary to discern the relevant symbols.

Wittlich *et al.* achieved recognition of solid notes, beams, slurs and bar lines by examining objects' dimensions, but no details were given.

3.3.7 Interaction and output

Pruslin's output took the form of text descriptions of note

clusters, including their sequence numbers and rhythm values. 153 clusters were tested and with the template matching threshold set at 70%, only one error occurred. 22 beaming complexes were examined, and all were correctly classified. In contrast, the output of Prerau's system took the form of DARMS (then called Ford-Columbia) data, with the intention that this should act as input to software for analysis, performance, display, printing etc. In the tests performed, output was 100% accurate, i.e. all symbols in the subset considered were recognised, and symbols - e.g. text characters - outside the scope of the program were identified as such. Andronico and Ciampa also produced music representational language encodings, but using TAU2-TAUMUS. They gave output for a single bar which was correctly recognised and also an example of partial recognition due to either incorrect binarisation threshold, poor print quality or presence of symbols which were outside the scope of the work.

Mahoney made use of interaction in developing and refining parametric descriptions of musical symbol primitives and characters (complex symbols) and in determining normalisation factors (this process was termed pre-calibration) which were then applied automatically. A detailed example of the analysis of an image was provided - the output simply taking the form of separate images containing particular categories of primitive or symbol. The vision system for the WABOT-2 robot had to be completely automatic, hence interaction was not an option open to Matsushima *et al.* For single pages of electronic organ score, complete processing times were given as 'roughly 15 seconds' and accuracy described as 'approximately 100%'. Output used a dedicated M.R.L.

compatible with the robot's limb control system. Various processing operations were undertaken in order to guarantee that the information passed to the robot control system was permissible and would not cause problems when driving the limbs of the robot (forcing it into attempting to cross hands for example).

Aoyama and Tojo gave an example of output after coarse classification for a single line of two-voiced music (the contents of one of their 'unit windows'), and two small detailed examples of complete analysis. The latter showed the correct separation of notes belonging to separate voices where the noteheads touched, and the distinction between the true tail and a spurious fragment in a stand-alone quaver after removal of thin vertically-orientated lines. In both cases the number and location of heads and beams was provided. An example of data in the format used by the folk-music database of Nakamura *et al.* was given by them as the result of recognising a few bars of monophonic notation, together with a screen display of the original and its reconstruction in conventional notation, derived from the above data. Pitch (octave number and semitone offset) and rhythm value only were stored.

Roach and Tatem provided a general discussion of the result of processing their six small test images, as no music representational language data was produced. All stave and ledger lines were correctly classified as horizontal lines, as were the centre portion of some long slurs and fragments of noise. Holes were categorised as large or small using the number of constituent pixels and a threshold. Some of the holes were not, as hoped,

hollow noteheads or part of a sharp, flat or natural sign, but were formed between a quaver tail and its stem. A significant proportion of the number of noteheads found by the blob detector (applying the circularity measure mentioned previously) had the notehead detected at a lower position than its true one, which meant the wrong pitch would have been assigned. Curves were detected, but only by selecting a threshold for curvature which worked for the test images, but, the authors stated, would not necessarily have been appropriate in the general case. When the writing in the original was poor, problems were encountered with loss of information as a result of segmentation, for example partial beams not distinguished from stavelines. Interestingly, back-tracking was available in some situations, so that the system could try alternatives once its original result had proved incorrect in the light of further data.

3.3.8 Error-checking/correction and future aims

Pruslin made the suggestion that error-correction could be introduced into his software, for example by testing for beaming complex thickness transitions from right to left as well as vice versa, and comparing results. Alternatively, he proposed, increased use could be made of context. He also stated the possibility of expanding the vocabulary of the program as a future aim. This was also Prerau's main concern for the future of his work. In order to extend the vocabulary of his program, a region would have to be added in the normalised feature space for each new symbol, a syntax test devised, and addition made to the output routine of the appropriate DARMS character. Prerau also stated

that it would be desirable to add the ability to recognise chords - perhaps based on Pruslin's algorithms - and to cope with larger format scores, trios, quartets, and so on. Prerau recognised that piano/organ music presented a more complicated situation (requiring 'a significant effort' in order to extend the software to cope with this sort of score) with symbols crossing from one stave to another, etc. He also proposed that the fragmentation and assemblage method of dealing with 'qualitatively defined interference' (the stavelines) might possibly be useful in other applications.

Andronico and Ciampa also looked to extend the capabilities of their program - to include reading different types of score containing a larger range of symbols, by extending the two grammars used. Mahoney said that expansion of his system to include new descriptions for symbols and formats was possible, and further testing was needed to enable evolution of the system. For instance, musical symbol descriptions needed to be derived from the primitives and the relationships between them. Also, more testing was required in order to define the limits for input quality and recognition accuracy. A convenient image input system was required too, with the inherent trade-off between image size and resolution. Program optimisation, the need for pre-processing and finding a method for dealing with 'complex characters' (clefs, sharp/flat/natural signs, etc) were other proposed topics for future work.

Matsushima *et al.* did not speculate on future aims, although their work has since involved incorporating a braille score

production facility into the system [Hewlett 1987, 1988], and a third WABOT is under development [Matsushima 1987]. Text recognition of Italian terms was Aoyama and Tojo's next priority. They proposed the use of the number and size of the constituent letters as a possible method for realising this aim. Nakamura *et al*, besides expanding the capabilities of their system, aimed to further classify and compare the folk-music contained in the resulting database.

Wittlich *et al*. originally aimed to expand the vocabulary of their system, but the project was ended due to the large amount of time spent in producing the processing programs, anticipated problems in generalizing recognition routines, and difficulties experienced in obtaining high-quality microfilm [Byrd 1984]. Roach and Tatem did not outline future work, but simply stressed that their results were improved as a result of using domain knowledge in low-level processing - as opposed to the more common practice of applying this knowledge at high level.

4. A System for the Automatic Recognition of Printed Music : Techniques

4.1 ACQUISITION OF THE BINARY IMAGE

In the course of this work, sample images have been acquired using a modified Canon 9030 laser copier, a flat-bed, CCD-based device with a maximum image size of A3 (420 x 297 mm), automatic thresholding and operator-selectable resolution (up to 400 d.p.i.). More recently, a Hewlett Packard Scanjet (also a flat-bed, CCD-based scanner) has been used, although this was limited to 300 d.p.i., A4 (297 x 210 mm) sized images. Thresholding was again done automatically, although a contrast control was available via the Scanjet driver software (which was normally set to 'darken'). The first images, scanned at full 400 d.p.i. resolution, included a variety of score formats (layouts and font sizes) from a solo instrument part through solo instrument with piano accompaniment to full orchestral score. Monophonic and polyphonic forms of music were thus included. The images also included examples of poor-quality print and symbols such as very long, almost horizontal slurs and similarly-dimensioned multiple beams, chosen to thoroughly test the recognition routines. The resulting 400 d.p.i. binary images each consisted of 4680 rows of 3344 pixels, requiring nearly 2 Mbytes of storage per A4 page using bit-per-pixel representation. The highest possible resolution was used initially despite the greater processing time involved in manipulating larger amounts of information. This was to some extent alleviated

by the fact that only small portions of a complete page were used while developing routines - a situation suited to the limited size of display devices available (maximum 1024 by 768 pixels). Experience showed that in general 300 d.p.i. (the resolution used most extensively) was perfectly adequate, but that 400 d.p.i. or higher was desirable when dealing with small notation (cues, for example) or exceptionally poor quality print, or indeed a combination of the two. It had to be borne in mind that a reduction in resolution from 400 to 300 d.p.i. (or even 300 to 200 d.p.i.) almost halved the amount of data involved. A reduction of resolution to 200 d.p.i. did however result in significant loss of detail and was not used in this work.

The first operation used (optionally) on an image was one of pre-processing using a horizontally-orientated low-pass filter. This filled gaps of up to ϕ pixels between set (black) pixels within individual horizontal lines and had the effect of removing short breaks in both stavelines and symbols. The maximum value of ϕ used was four. This filter will be mentioned again later when discussing structural segmentation techniques and line-following algorithms.

4.2 EXPERIMENTAL SEGMENTATION

As mentioned in section 3.3.4, the first step in segmenting any image of printed music involves locating the stavelines which are a mandatory component of all scores using conventional music notation. As a preliminary experiment, a test image was chosen so that any stavelines present in the image were horizontal, although

for several reasons this is often not the case. It did, however, enable the simple technique of forming the histogram of the horizontal sums of black pixels to be used as the basis of an elementary stave-finding routine. Once the histogram had been obtained, groups of five peaks were easily detected, indicating the presence of staves. Allocation of pixels to stavelines could then be achieved by obtaining another histogram, in this case of the height of the vertical runs of black pixels which crossed a row indicated by the staveline-finding procedure. By tracking across the image in the appropriate rows and marking all vertical runs of black pixels whose height was below a threshold derived from the second histogram, the staveline pixels could be found.

This method had several major weaknesses, but its implementation provided some important indications of the problems involved in segmenting an image of printed music, some of which appeared to be unique to the subject. Firstly, it could not be assumed that stavelines were horizontal across the whole page - nor indeed that they continued across the whole page - which in itself invalidated use of the horizontal-sum histogram. Secondly, the setting of a fixed threshold for the thickness of a staveline (i.e. the vertical run of pixels which were to be marked as staveline pixels) would take no account of local thickness maxima. Consequently, a single run of pixels which exceeded a given thickness threshold would be treated as symbol rather than staveline, despite the possibility that in context this could be obviously incorrect. Thirdly, although the stavelines may have been horizontal on the original printed page, there was no guarantee that the page was exactly level when scanned.

Consequently, the image may have been slightly skew - and a rotation of less than 30' could cause the peaks of the horizontal-sum histogram to merge, rendering the technique useless. Other problems arose, such as determining the extent to which a symbol coincided with a staveline. For example, where a notehead was situated in a stave space, i.e. overlapping two stavelines, the shape of the isolated notehead would vary depending on the amount of overlap assumed by the staveline extraction process. This would, in turn, have a bearing on the recognition routines, which would need to be immune to such variations. Similarly, but more significantly with regard to recognition, where part of a symbol coincided completely with a staveline and was below the threshold value for maximum staveline thickness, this part would be categorised as staveline rather than symbol. The highest part of the main section of a bass clef is a common example of this situation, as is the portion of the treble clef which normally coincides with the lowest of the five stavelines.

It was thus deemed necessary to develop a means of segmenting an image which would enable location of the stavelines regardless of a reasonable amount of rotation of the image (say +/- 10°) whilst also coping with slight bowing of stavelines and local thickness maxima. Ideally, 'regional information' would also be produced which could be used in determining whether a symbol had merged with a staveline.

4.3 SEGMENTATION

It should be pointed out that an advantage of the method described in this section is that the image breakdown achieved serves not only in finding stavelines but also in providing structural analysis of symbols and in providing a convenient method of manipulating the components of the image.

The segmentation technique which was employed made use of an original transformation (developed in the course of this work) of the line adjacency graph (LAG) [Pavlidis 1982], which was obtained directly from a run length encoding of the binary image. Two passes were made over the data in order to achieve segmentation. The first produced the run length encoded version of the image, with the runs of pixels (segments) orientated vertically (figure 4.1). The second pass constructed the transformed LAG. Although the two stages could have been combined, they were kept separate because some scanners produce run length encoded data directly, thus obviating the need for stage one. Also, for reasons of efficiency, the transformed LAG was produced directly from the run-length encoding rather than creating the LAG and then subsequently performing the transformation. The LAG has been used successfully elsewhere as the basis of pattern recognition systems for Chinese characters, English text, and electrical circuit diagrams, as described in section 3.2.

By proceeding from left to right across the image and considering pairs of columns of run length encoded data, the segments were grouped together to form sections (nodes of the transformed LAG). If a segment existed in the right hand column

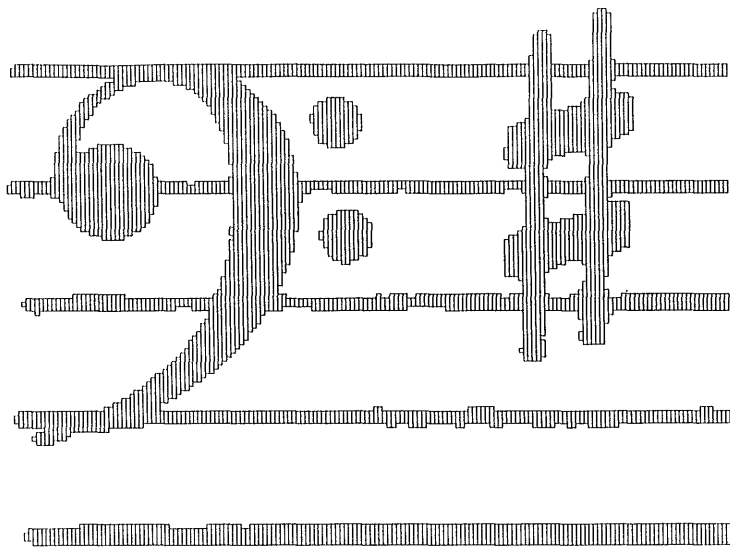


Figure 4.1 A fragment of an image showing the boundaries of the segments formed by vertical run-length encoding.

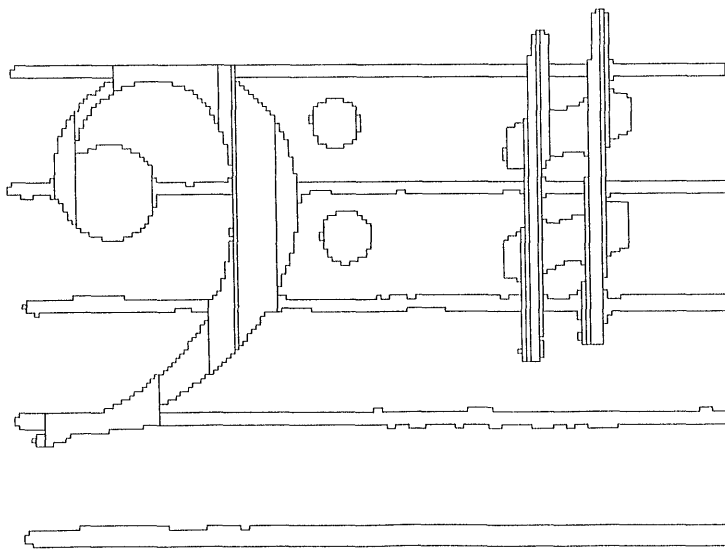


Figure 4.2 The image fragment of figure 4.1 showing the boundaries of the sections (the nodes of the transformed LAG).

and did not overlap a segment in the left hand column, a new section was created and the segment allocated to that section. If the reverse was the case (i.e. the segment was in the left hand column and unconnected) then the section to which the segment belonged could be terminated. If a pair of segments were single-connected to each other then the right hand segment could be allocated to the section of the left hand segment. The other possibility was a multi-way junction, where a single segment in one column overlapped more than one segment in the other column. In this situation the appropriate section or sections were terminated (left hand column) or initialized (right hand column). When the transformed LAG of an image of printed music was produced, some of the nodes of the graph corresponded to structural components of the musical symbols. This correspondence was improved by the addition of one further rule. This required that the section which was currently being processed would be terminated if the ratio of its average thickness (segment height) to the height of the next segment to be added to that section exceeded 2.5 : 1. If this was the case, then the next segment was allocated to a new section. Otherwise, for example, the right-most part of the bass clef symbol would form a single section with the staveline on which it was superimposed (figure 4.2) as would black noteheads (figure 4.3).

Using this segmentation technique resulted in a fundamentally consistent sectioning of the image regardless of limited rotation of the original (figure 4.4). In addition, subsequent processing operated on the section data, giving a significant increase in speed over a technique operating on individual pixels (see section

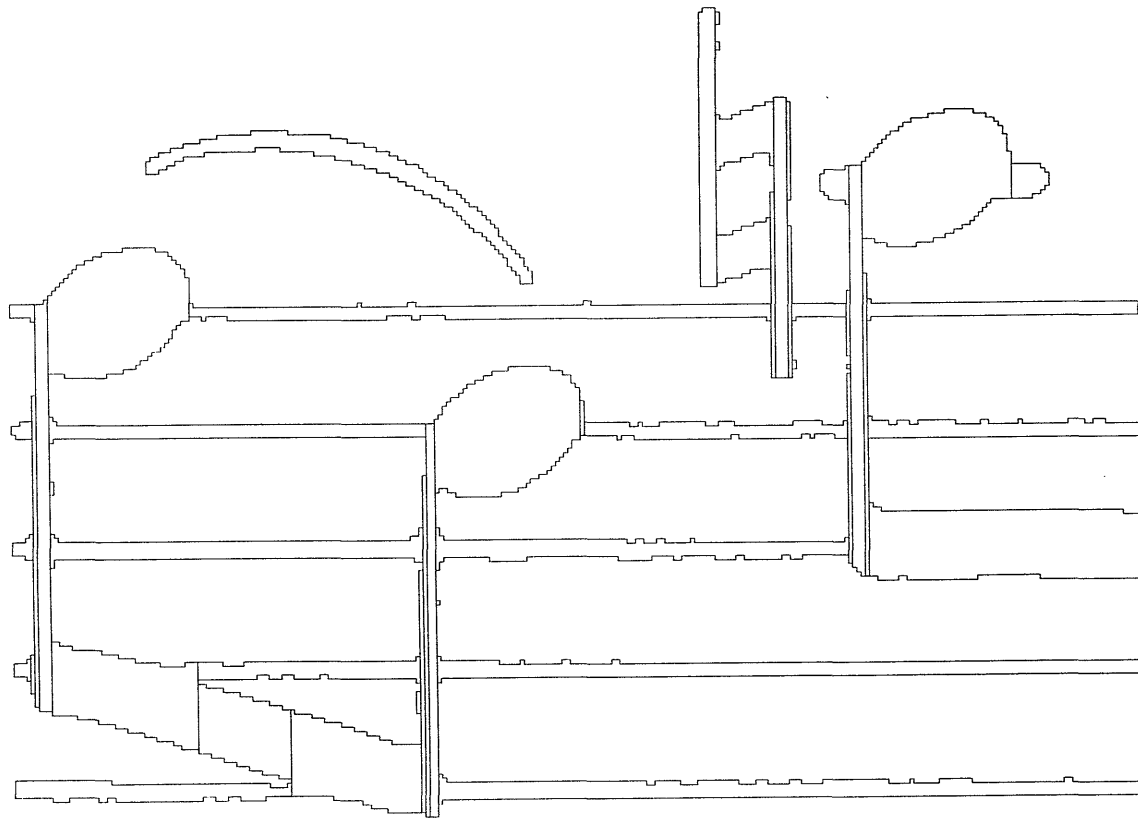


Figure 4.3 A larger image fragment with sections indicated.

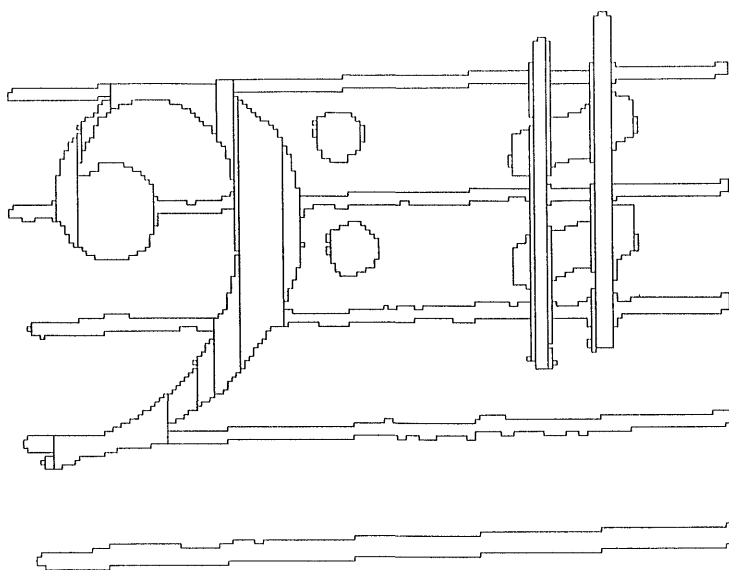


Figure 4.4 The boundaries of the sections for a rotated version of the image fragment shown in figure 4.1.

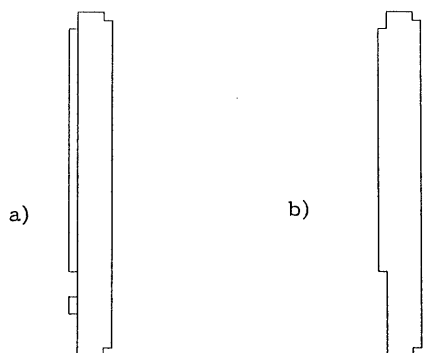


Figure 4.5 The process of merging sections after noise removal.

3.3.4 regarding Roach and Tatem's work). Various attributes of the section were stored together as an entry in a data structure. These included, for example, x-minimum, x-maximum, y-minimum, y-maximum, a pointer to a segment list (containing the y-ordinates of the start and end of each run of pixels), area (number of set pixels), pointers to lists of forward and backward connections to other sections, and various summations which were used in calculating a least squares fit straight line through the mid-points of the segments.

4.4 NOISE REMOVAL

All sections with a small area (λ pixels or less, where λ was commonly five for a 300 or 400 d.p.i. image) which had no connections or one connection - either forwards or backwards - were removed as noise. As a result of removing a single-connected noise section, the section to which it was connected may itself have become single-connected. In this case, the sections involved were merged if a multi-way junction in the original image had now disappeared, provided that the thickness ratio test originally applied when producing the transformed LAG was satisfied. For example, in figure 4.5a, there is a noise section attached to a vertical stroke. After removal of the noise section, the two remaining sections would be single-connected. These would then be merged into a single section as shown in figure 4.5b. To reiterate, merging did not take place if a multi-way junction still remained despite the removal of the noise section, or if the thickness ratio between the two sections was greater than 2.5 : 1.

4.5 FILAMENTS AND STAVELINE FINDING

In order to find potential staveline sections (filaments), a search was made of the section list to find those which fulfilled the following criteria :-

- i) aspect ratio (i.e. length / average thickness) $> \alpha$
 - ii) forward and backward connected
 - iii) curvature (variance figure produced by least squares fit) $< \beta$
- Figures for α and β used were, respectively, 10 and one.

Test i) selected sections which were relatively long and thin without introducing any absolute measurements. Consequently, some sections which were long beams were included as potential staveline sections. These were filtered out at a later stage by forming a histogram of filament thickness over the complete page and deriving a cut-off point for permitted thickness. The threshold used was 'mean + 3 x standard deviation', as indicated in figure 4.6.

Test ii) was aimed at eliminating other relatively long and thin lines which were not fragments of staveline but which may have occurred in an image of printed music and which would not be filtered out by the above procedure. Examples included markings for crescendo and diminuendo ('hairpins'), text prolongation, part overlap indication (e.g. in vocal short score) and other less common symbols. Often, sections originating from the above examples would be single-connected, whereas true staveline sections would normally be connected both forwards and backwards.

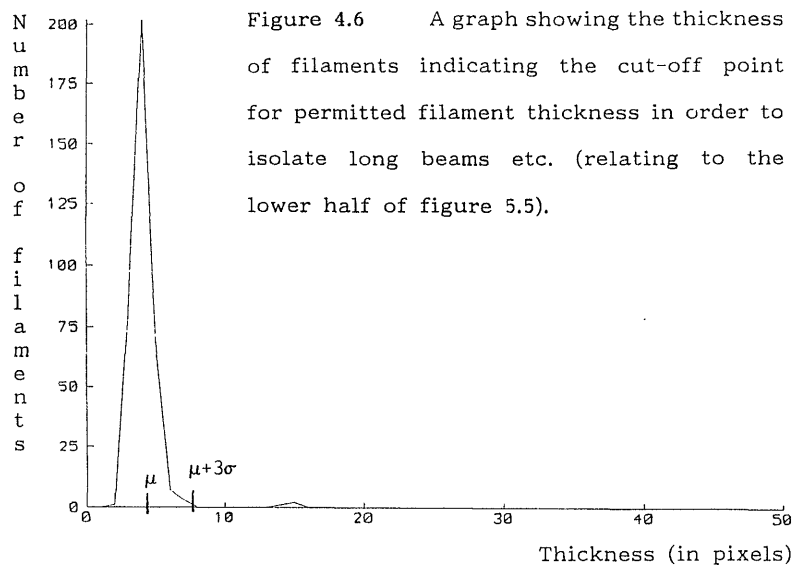


Figure 4.6 A graph showing the thickness of filaments indicating the cut-off point for permitted filament thickness in order to isolate long beams etc. (relating to the lower half of figure 5.5).

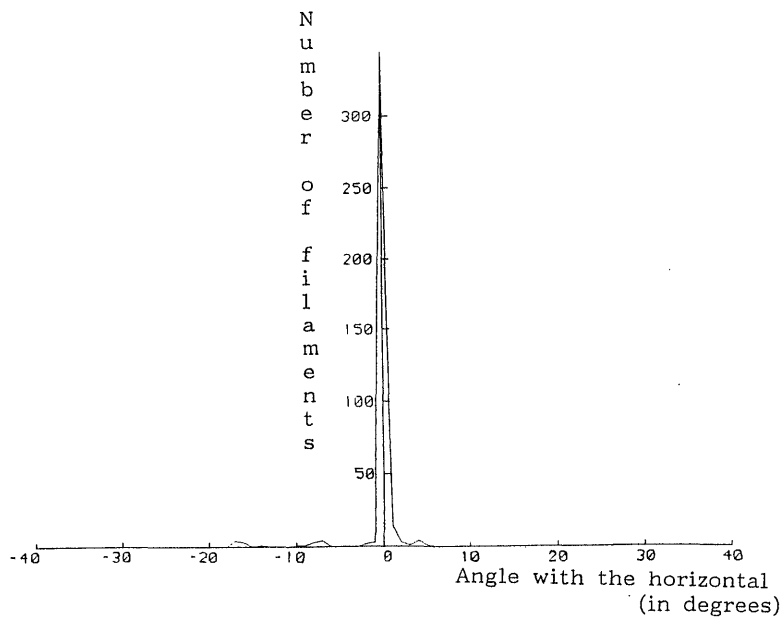


Figure 4.7 A graph showing the angle formed between the centre-line of filaments and the horizontal (relating to the lowest system of figure 5.5).

Unfortunately, due to poor print quality, breaks in stavelines occurred quite frequently. This produced single-connected staveline sections, hence the pre-processing stage described previously. This alleviated the problem to a large extent because breaks were often very short. It did become apparent, however, that it was more appropriate in the general case to alter test ii) to 'single-connected', thus eliminating some non-staveline filaments which were zero-connected but permitting true staveline filaments which had an adjoining break. This meant erring on the side of including some incorrect (i.e. non-staveline) filaments rather than excluding correct filaments. A significant number of non-staveline filaments may also be eliminated by using a histogram of the angles formed by filament centre-lines and the horizontal, for the whole page (figure 4.7 shows this for part of the image in figure 5.5). Even if the page was rotated (within the permitted tolerance) a main peak would show the large number of staveline filaments at one angle, whilst hairpins etc., could normally be excluded.

Test iii) removed slurs which were both long and thin and also cut through other symbols (making them connected), because they had a high curvature value - obtained as part of the least squares fit procedure. The curvature threshold had, however, to be high enough to include bowed stavelines, and the value of β given above was found to satisfy this aim when using the test images.

4.6 FILAMENT STRINGS AND STAVE FINDING

In order to establish the presence of a stave, five

horizontally overlapping and roughly equi-spaced filaments had to be found. The obvious way of achieving this involved stepping through the filament list and comparing the filament under test with as many of the other filaments as was necessary to determine whether or not it formed part of a stave. In the system under discussion, this process was simplified and hastened by concatenating the filaments into filament-strings, which then underwent the requisite tests.

The centre-line of each filament was projected to the right by a distance of $0.25 \times$ the length of the filament and tests made to detect the presence of another filament within \pm twice the mean filament thickness on either side of the projected centre-line. If such a filament was present, then it was combined with the current filament to form a filament string. All filaments which were included in a filament string were flagged to eliminate them from further testing. When the list of all the filament strings in the image was complete, each was tested to establish the number of concurrent (i.e. horizontally overlapping) filament strings. These, assuming they existed, were then measured for vertical spacing from the filament string under test and a list of spacings established. A best fit was obtained for the spacings between the filament string under test and, if possible, four of the others in the list, with a threshold for the maximum spacing. A threshold had to be set for the maximum possible spacing otherwise matches could have been made between stavelines from different staves and possibly also with hairpins. It would have been inappropriate, in order to prevent this, to invalidate a match because an extraneous filament existed within the potential

stave, as this could be a valid situation. For example, a hairpin might be superimposed on a true stave.

Once a stave had been found, each staveline was tracked across the page in both directions and all sections which fell within the projected path of the staveline and were below the threshold for permitted filament thickness were flagged as staveline sections (figure 4.8). The tracking was achieved by using the section connections obtained from the transformed LAG in conjunction with local centre-line projections. This structural method could also traverse breaks in stavelines which remained despite the pre-processing.

After all the staves present in the image had been found, and all stavelines tracked to their full extent across the page, a restructuring of the transformed LAG was performed. This involved stepping through the section list and categorizing sections' forward and backward connections into staveline and non-staveline sections. Consequently, the sections' data records also contained pointers to lists of forward and backward connections to staveline sections. Merging was again undertaken, as described in section 4.4, in this instance where non-staveline sections had now become single-connected - ignoring connections to staveline sections - and the thickness ratio test was passed. Musical symbols were now, in effect, isolated from the stavelines (figure 4.9).

4.7 SIMPLIFICATION OF THE TRANSFORMED LAG

Even after noise removal, the transformed LAG contained

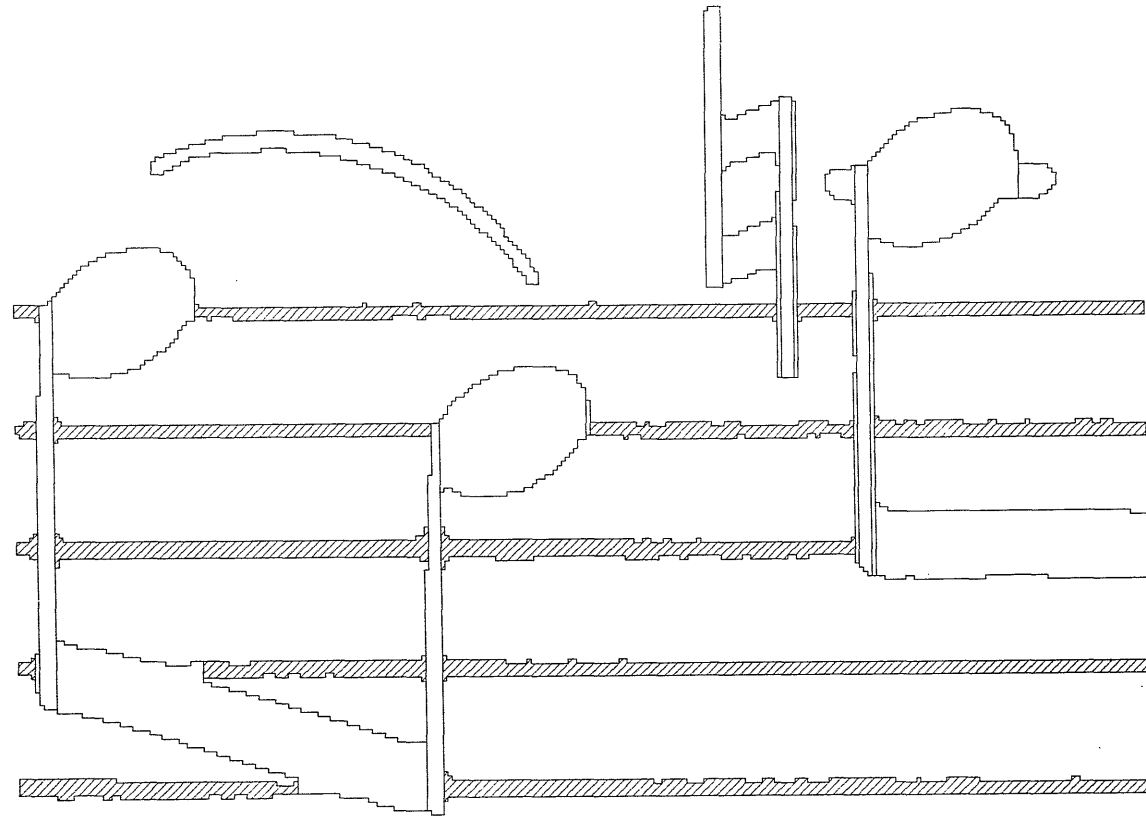


Figure 4.8 The image of figure 4.3 with the staveline sections indicated and showing where the remaining sections have been merged as appropriate.

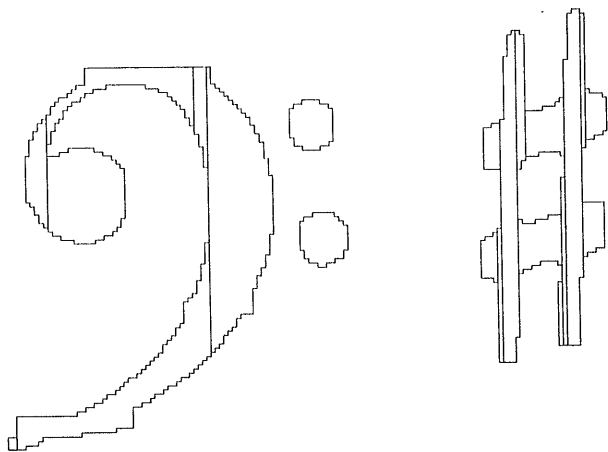


Figure 4.9 A sectioned image fragment with the staveline sections removed.

numerous non-staveline sections which did not represent structurally significant parts of the image. Mostly, these had a high vertical aspect ratio and were either the result of parts of the image forming a small angle with the vertical (and hence with the run length encoding) or short breaks in vertical runs of pixels (see, for example, figures 4.8 and 4.9). This led to the development of two approaches to further processing. The first is outlined below, while the second is detailed in section 4.11 (ANALYSIS OF BEAMED NOTE GROUPS). As part of further development work, the two techniques will be integrated within the system to give complimentary tools for use in processing symbols.

As a result of the nature of the structurally insignificant sections, any section which fulfilled the following criteria was removed from the transformed LAG:-

- i) Vertical aspect ratio $\geq \delta$
- ii) Single connected to a section which either :-
 - a) has a bounding rectangle larger than or equal to that of the section under test
 - or
 - b) has a vertical aspect ratio $\geq \delta$ and its area is greater than that of the section under test

(if the section was single connected in *both* directions then the section was removed if *either* connection satisfied test ii)).

The value of δ used was five.

When a section was removed as part of the above process, the appropriate inter-section connections were maintained. The

non-staveline sections in the resulting transformed LAG were almost entirely sections which were structurally significant.

4.8 OBJECT FORMATION

An object was considered to be a group of connected sections (references to connections now refer to connections to non-staveline sections only), details of which were stored together in a data structure. Figure 4.9, for example, contains four objects. Objects were found by stepping through the section list, ignoring staveline sections, and commencing a depth-first traversal of the transformed LAG at each section which had not already been included in an object. An algorithm for depth first graph traversal based on that given in the work of Hopcroft and Tarjan [1973] was used. Various statistics were established for each object as the traversal took place and were stored as members of the object data structure. These included co-ordinates of the bounding rectangle, area (sum of constituent sections' areas), and number of sections which comprised the object.

4.9 SYMBOL ORDERING

Each object (single symbol or overlapping symbols) in the object list was ordered with respect to the complete page, i.e. left to right, and bottom up within columns, as a result of its derivation from the section list. Hence, the ordering of the object list bore no relation to the musical structure of the image. Each object had associated with it one or more stave numbers which were found during the object formation process by

referring to the stave number of each of the staveline sections connected to the sections which made up the object. Using the object stave number (or numbers), the symbols could be organised by stave and ordered, simply, from left to right. A separate group of objects contained those which did not come into contact with a staveline, for example semibreves on ledger lines, dots of various kinds and some slurs (figures 4.10 and 4.11). This method of initial ordering normally accounted for a large proportion of the notes, rests, clefs and barlines in any image and only omitted symbols such as 'free-standing' slurs whose implied 'connections' needed to be established by a separate process. The spatial organisation of musical symbols - and indeed the significance of this - becomes far more complex when dealing with keyboard music, say, where voices will sometimes cross from one stave to another and simultaneous events will not necessarily be vertically aligned. These problems will be the subject of future research activity.

4.10 RECOGNITION

A combination of several techniques was used in order to achieve recognition (figures 4.10 and 4.11). Simple symbols such as crotchets, barlines, accidentals and quaver rests could be recognised by the size of their bounding rectangle and the number and organisation of their constituent sections. For example, a crotchet on the stave normally consisted of just two sections, one of which had a high vertical aspect ratio (the stem) and the other an average thickness slightly less than the staveline spacing. The pitch of the note could be found by either examining the staveline

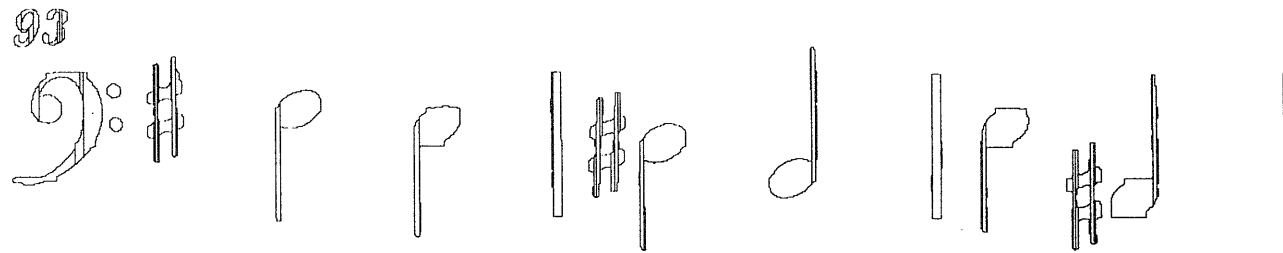
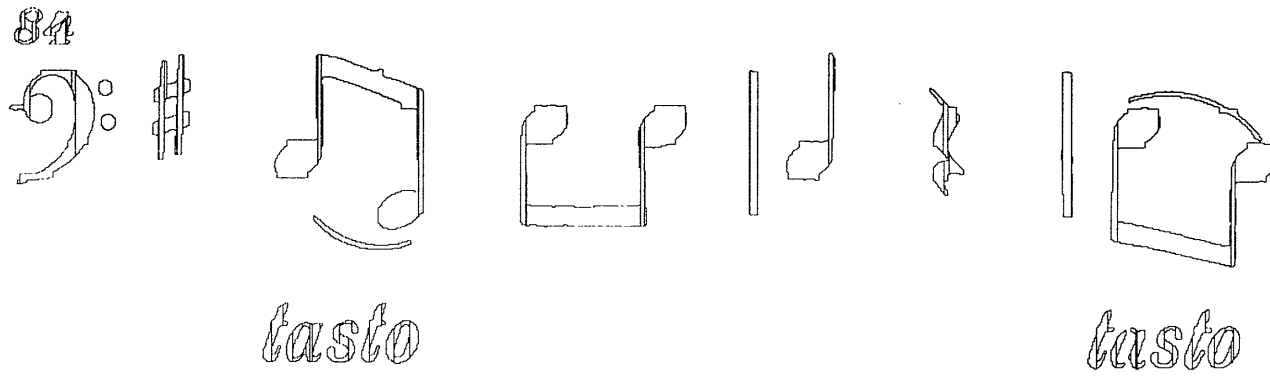


Figure 4.10 A larger sectioned image fragment with the staveline sections removed.

```

*****STAVE 1*****
OBJECT 1 :
OBJECT 11 :**Sharp**
OBJECT 14 :**Crotchet - stem down**
fstavenum = 1
staveline = 14
OBJECT 21 :**Crotchet - stem down**
fstavenum = 2
staveline = 13
OBJECT 23 :**Barline**
OBJECT 24 :**Sharp**
OBJECT 25 :**Crotchet - stem down**
fstavenum = 1
staveline = 13
OBJECT 27 :**Crotchet - stem up**
bstavenum = 1
staveline = 12
OBJECT 30 :**Barline**
OBJECT 31 :**Crotchet - stem down**
fstavenum = 2
staveline = 13
OBJECT 33 :
OBJECT 35 :**Crotchet - stem up**
bstavenum = 2
staveline = 11
OBJECT 43 :**Barline**
*****STAVE 2*****
OBJECT 4 :
OBJECT 12 :**Sharp**
OBJECT 15 :**pair of beamed quavers, stems up**
OBJECT 17 :**Slur**
OBJECT 22 :**pair of beamed quavers, stems down**
OBJECT 26 :**Barline**
OBJECT 28 :**Crotchet - stem up**
bstavenum = 2
staveline = 22
OBJECT 29 :**Crotchet rest**
OBJECT 32 :**Barline**
OBJECT 37 :**pair of beamed quavers, stems down**
OBJECT 39 :**Slur**
*****STAVE 3*****
OBJECT 2 :
OBJECT 3 :
OBJECT 5 :
OBJECT 6 :
OBJECT 7 :**Dot**
OBJECT 8 :**Dot**
OBJECT 9 :**Dot**
OBJECT 10 :**Dot**
OBJECT 13 :
OBJECT 16 :
OBJECT 18 :
OBJECT 19 :
OBJECT 20 :

```

Bass Clef

Sharp

Bass Clef

*Figures
indicating
bar
numbers*

All

these

```

OBJECT 34 :
OBJECT 36 :
OBJECT 38 :
OBJECT 40 :
OBJECT 41 :
OBJECT 42 :

```

objects

are

text

Notes

The items in italics have not been recognised - in all cases except object 33 because they are outside the scope of the current recognition routines. *fstavenum* is the number of forward connections to staveline sections from a particular note head. Similarly for *bstavenum* and backward connections. *staveline* is a code number, the first digit of which is the object's stave number while the second is the number (from one to five, one being the lowest) of the staveline to which the note head is connected (the lower staveline, if there are two connections).

Figure 4.11 Output from the original recognition routines, relating to the image in figure 4.10.

number of the staveline section(s) connected to the notehead section, or - considering the possibility of breaks between notehead and staveline - the vertical position of the centre of gravity of the notehead section with respect to local staveline sections. The sharp sign which has not been recognised in figure 4.11 has had one of its structurally significant sections removed by the staveline-finding routine. Only models of ideal forms of symbols were used at this stage, to show how successful the application of these could be given the structural breakdown provided by the transformed LAG.

These models were used in conjunction with rules which specified relevant dimensions or spatial organisation for the constituent sections. Each model consisted of the number of sections which constituted the ideal form of the appropriate symbol, together with the number of forward and backward connections for each section. This form of model only guaranteed a one-to-one correspondence between model and symbol type for the sub-set of notation being processed, i.e. it was possible that a match existed between a model and a symbol outside this sub-set. Models were included for the following single section objects:- slur, barline and dot. A high (> 5) horizontal aspect ratio was used to indicate a slur, a high vertical aspect ratio indicated a barline and a single-section object which satisfied neither of these conditions and was enclosed within a bounding rectangle with side length less than the stave space height, was classified as a dot.

An object consisting of two sections was classified as a

crotchet. If the first (i.e. leftmost) section had a high vertical aspect ratio, it was deemed to be the stem, and the crotchet described as 'stem down', otherwise the stem direction was taken to be up. A further test checked the average thickness of the other (notehead) section, confirming that this was less than or equal to the stave space height.

Three types of eight-section object were included; a sharp sign, a group of three beamed quavers and a crotchet rest. The number of forward and backward connections of each constituent section were used to make the distinction between the first two symbols, while the presence of a high vertical aspect ratio section as the first (leftmost) section as part of the beamed group indicated 'stems down'. If neither set of connections was appropriate and the width of the bounding rectangle was equal to the stave space height $\pm 20\%$, whilst the height was between three and four times the stave space height, the object was classified as a crotchet rest.

A four-section object was deemed to be a flat or natural, provided its vertical dimension was between two and three times the stave space height. The ratio of the average height of the first (leftmost) and last (rightmost) sections was used to distinguish the two symbols; 1 : 0.8 or greater indicating a flat.

Five-section objects which were modelled included a quaver rest and a pair of beamed quavers. The list containing the numbers of forward and backward connections for each constituent section were used to distinguish between the symbols. The same test as that used on the group of three beamed quavers was used to detect

stem direction within the beamed group and an optional check for the presence of noteheads, using the average thickness measure, could have been added. A model for the main portion of the bass clef was later added to this category.

To summarise, the above implementation enabled recognition of the following types of symbol:- slurs, barlines, dots, crotchets, sharp, flat and natural signs, quaver and crotchet rests, bass clefs and beamed groups of two or three quavers. Figures 4.10 and 4.11 provide an illustrated example of recognition results achieved using this representative selection of symbols. All the above relied upon the isolated object having the correct topology, and, as shown in figure 4.11, this was not necessarily the case.

More complicated symbols such as beamed note groups needed more effort in order to achieve correct classification. A separate algorithm was developed which examined all beamed note groups, counting ledger lines and beams as it proceeded. This was achieved regardless of beam fragments occasionally running together due to the printing process, which removed the correspondence between single beam sections in the transformed LAG and beam fragments in the image which ran from note stem to note stem. This approach was, however, found to be too vulnerable to rotation of either the individual object or the entire image, so an alternative method was devised, as described in the following section.

Output was originally in the form of a text description of the recognised symbols. The categorisation of symbols by stave (outlined in section 4.9 above) can be seen in figure 4.11 - the third group of symbols are those which were unconnected,

physically, with a stave. This form of output was convenient for providing feedback during the debugging process but needed to be

replaced by M.R.L. data for practical use, i.e. interfacing with other software. No M.R.L. was used until the last possible opportunity, to avoid tying the system to a particular representation scheme and to keep the M.R.L. data production stage as a self-contained module which could be replaced as required. A detailed discussion of the SCORE desktop music publishing package and examples of uses of its M.R.L. in conjunction with the author's system are included in chapter 5. SCORE was chosen as the most comprehensive music printing software package available and also because the M.R.L. used within the package was fully documented.

Overlapping or superimposed symbols will have to be separated out by a specific algorithm. Proposals for this are given in chapter 5. This is similar to the not insignificant problem of character separation [Kahan 1987] but far more complex due to the 2-D organisation of music notation (see section 3.2 for further comparisons regarding dimensionality).

4.11 ANALYSIS OF BEAMED NOTE GROUPS

Initially the method for simplifying the transformed LAG outlined above was applied to beamed note groups. It was found that this approach was not robust enough to cope with the general case because it relied upon the notestems involved being very nearly vertical (sections with high vertical aspect ratio were identified as note stems and analysis proceeded on that basis). This approach had to be considered inadequate because the assumption was often not true, especially in the case of long

notestems and also when considering the original aim of making the system immune to rotation of $\pm 10^\circ$. With this in mind, and also in an attempt to benefit from the success achieved in segmenting stavelines irrespective of imperfections including rotation, a new approach was devised. This was based on the same transformed LAG as had been used previously, but with the segments (the continuous runs of pixels in the run-length encoding) orientated horizontally. An investigation into the feasibility of deriving the new transformed LAG from the original section data for the object showed this to be inefficient and, in any event, unnecessary. Instead, the operation was implemented simply by reconstructing the object in a separate image (figure 4.12), and applying a new routine for run-length encoding together with the original sectioning routine. The horizontally-orientated run-length encoding of the object in figure 4.12 is shown in figure 4.13 and the new sections derived from this data are shown in figure 4.14. The new transformed LAG could then be searched for sections with high aspect ratio - a feature taken to indicate a vertical line, in this case a notestem.

Those sections with an aspect ratio greater than or equal to γ (where γ was equal to five) were selected as vertical lines and have been removed in figure 4.15. This then left the noteheads and the beaming complex (a single beam or a combination of multiple or partial beams treated as a single unit). These components were, however, to be represented using section data based on the original orientation of run-length encoding, as this would more closely resemble the underlying structure. Again, a feasibility study was undertaken, and the possibility of deriving the required

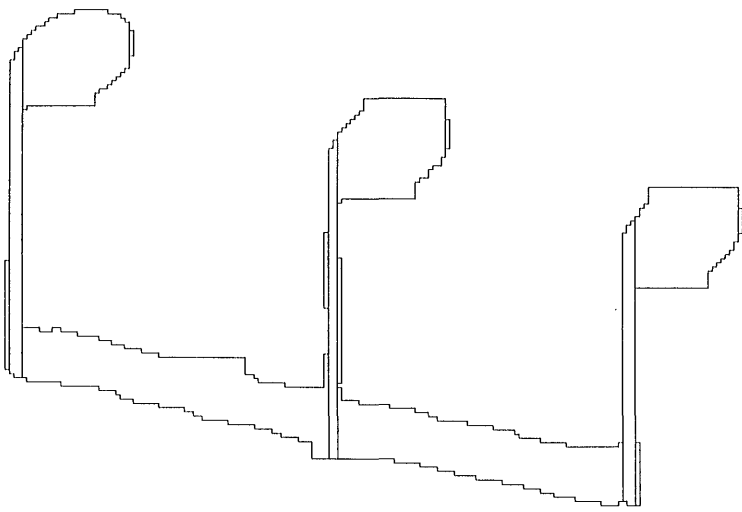


Figure 4.12 A sectioned beamed note group (with noise sections removed).

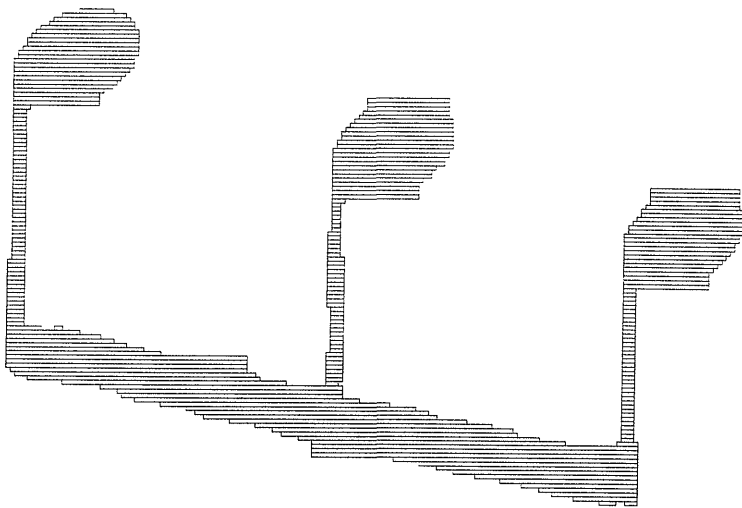


Figure 4.13 The object from figure 4.12 run-length encoded with the segments orientated horizontally.

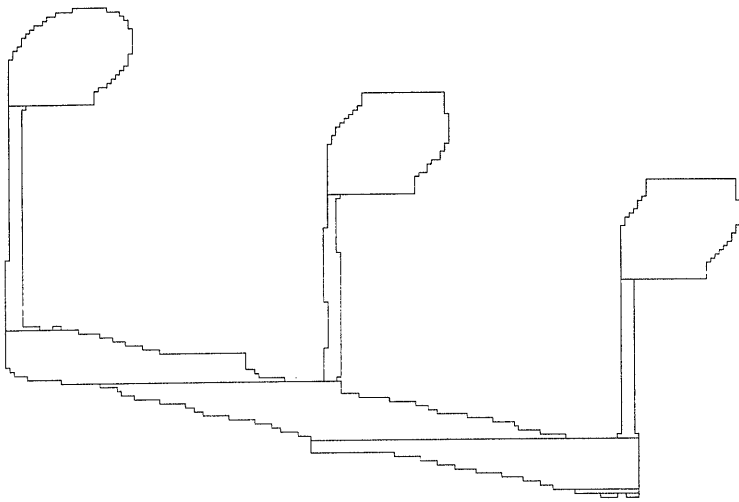


Figure 4.14 The sections derived from the run-length encoding of figure 4.13.

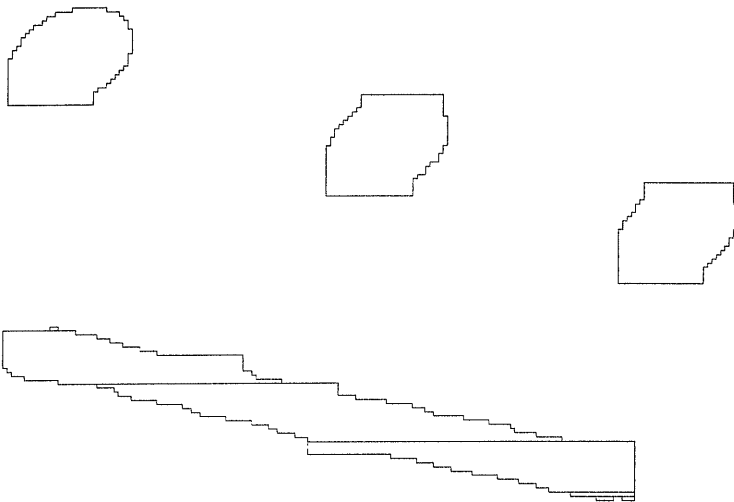


Figure 4.15 The high aspect ratio sections removed from those shown in figure 4.14.

section data by operating on the original section list for the object was examined. This would have entailed removing from the corresponding sections those complete or partial (vertical) segments which lay within the region of the object designated as 'notestem' and merging, removing or creating sections as necessary. The number of possible permutations of these last three operations made this a complex option to implement. In contrast, the chosen method simply involved erasing the notestem sections in the image containing the reconstructed object (as in figure 4.15) and then re-sectioning the remaining parts of that image using vertically-orientated run-length encoding (figure 4.16). The direction of the notestems was then found by searching to the left of the first (i.e. leftmost) notestem for a notehead. The search region was defined as having its right hand side formed by a line parallel to the centre-line of the leftmost notestem and its upper side a horizontal line extending from the lowest extremity of the notestem section. The other two sides of the region were formed by the edges of the image. If a section with an area greater than $(.5 \times \text{the average staveline spacing})^2$ was found, then this was taken to be a notehead and the notestem direction taken to be up, otherwise it was assumed to be down and a check was made for a notehead at the top and to the right of the stem.

The next stage involved forming the beaming complex into a single object by traversing the constituent sections using the same algorithm for object formation as had been used previously (section 4.8). The starting section for this was found by searching the section list for one which contained a pixel from the row adjacent to the appropriate end of the notestem region.

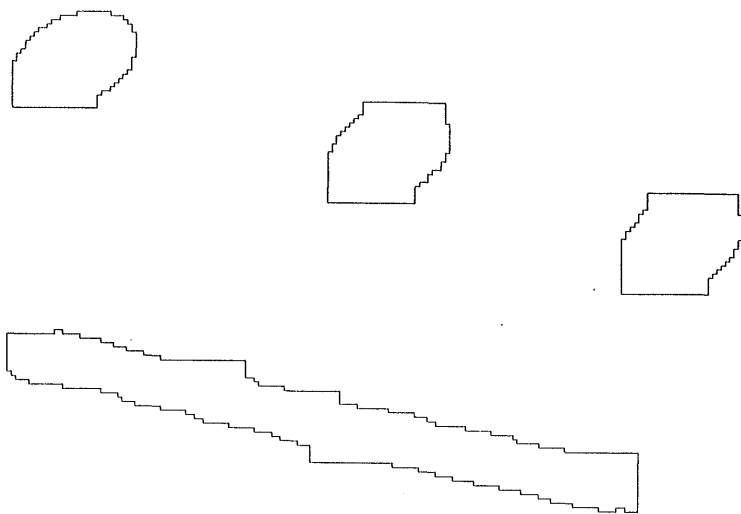


Figure 4.16 The image of figure 4.15 sectioned using vertically-orientated run-length encoding.

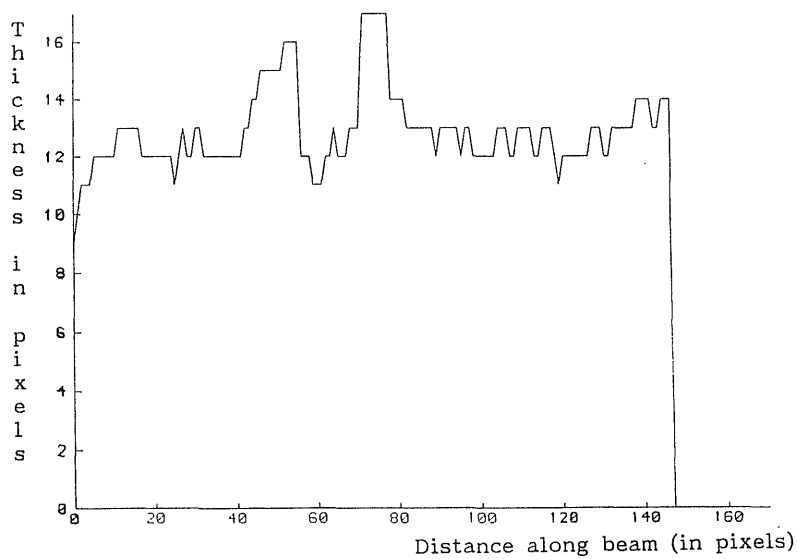


Figure 4.17 A graph of overall beam thickness for the beaming complex shown in figure 4.16. (The average staveline spacing relating to this object was equal to 21).

Once the beaming complex had been formed into an object, a list of values for thickness could be ascertained by establishing the lowest and highest parts of the object for each column over its entire length. The distance between each pair of points gave the thickness for that particular column (figure 4.17). By using this approach, it became irrelevant whether the notestems continued through a set of multiple beams or ended as they contacted the first of the beams, as is the case in some styles of engraving. Also, a break in one or more of a set of beams would not be of consequence provided that at least enough connections existed in order to preserve the connectivity of the constituent sections of the beaming complex. The rhythm values for the individual notes were determined by calculating the average overall thickness of the beaming complex in one or two regions, as appropriate, to the side of each note stem. The width of these regions was set equal to the average stave space height. If two measurements were taken (for an inner note of a beamed group of three or more notes) the larger of these was used in the following calculations. If the thickness was below ρ x the average stave space height, the note was taken to be a quaver, if more than this but less than $(1 + \rho)$ x the average stave space height then a semiquaver, and above this, a demisemiquaver. The value of ρ commonly used was one. These thresholds could be extrapolated to include shorter rhythm values.

This technique has proved reliable for the general treatment of standard notation but it seems that further analysis would have to take place if cue-sized notation was also to be processed. Investigation of the holes present in the beaming complex would

seem to be necessitated, a procedure which could also prove useful as a second source of information when dealing with standard-sized notation. The noteheads were found by searching either above and to the right of, or below and to the left of, each notestem, as appropriate, and applying the area criterion used in finding the initial notehead. Pitch was determined by examining the staveline section connections from the equivalent region in the original object. Again, this involved matching regions between different representations, in this case between the - now partially - reconstructed object and its original section list. Once the corresponding notehead section or sections had been found, the position on the stave could be determined from the stave number, or numbers, of the staveline section connection or connections. Alternatively, as mentioned previously, the relative positions of the centre of gravity of the notehead and the nearest staveline sections could be used.

This technique proved successful in that it was suitably robust given rotation of the object or image, or varying line thickness, length or straightness. As a consequence of this, the technique could also be usefully applied to other symbols containing vertically-orientated linear components. These include all individual notes with stems, barlines, quaver (and shorter duration) rests, sharp, natural, flat and double flat signs, boxes (surrounding bar numbers or text - see figure 5.1) and brackets.

As mentioned in section 4.7, the complete integration of the above approach with that of simplifying the original transformed LAG is a future aim. The overall robustness of the recognition

system should be significantly enhanced by this combined approach, because linear components will be appropriately sectioned whatever their orientation (given that the angle made with one version of the run-length encoding will have to be between 45° and 90°). Non-linear components have been seen to be appropriately sectioned by the original transformed LAG, thus giving a unified approach to object decomposition. Further discussion and examples of initial applications of this reasoning can be found in chapter 5.

4.12 SYSTEM PARAMETERS

The parameters of the system, which have previously been referred to using Greek letters, are listed together in this section for reference. The number in brackets following the description of each parameter is its most commonly used value.

α = minimum aspect ratio (i.e. length / average thickness) of a filament. (10)

β = maximum curvature (variance figure of least squares fit) of a filament. (1)

λ = maximum area of a noise section (in pixels). (5)

δ = minimum vertical aspect ratio (average thickness / length) for a section to be removed under the process of section 4.7 - simplification of the transformed LAG. (5)

ϕ = maximum number of continuous background (white) pixels (bordered by black pixels) in a horizontal row to be filled by the pre-processing low-pass filter. (4)

ρ = proportion of the average staveline spacing to be used as the threshold in differentiating different rhythm values when

analysing beamed note groups. (1)

γ = minimum aspect ratio for a section to be considered as a vertical line by the beamed note group analysis routine. (5)

The values for the above parameters were not rigid but those given in brackets above were found to be widely applicable. The avoidance, as far as possible, of the use of absolute measurements led to the adoption of aspect ratios (α , δ and γ) which preserved the size-independence of the system. Where pre-processing was used, the value of ϕ could be reduced with the advantage of diminishing processing time, while not having a very adverse effect on later operations. The value of λ could also be reduced, with similar effects.

5. A System for the Automatic Recognition of Printed Music : Worked Examples

5.1 INTRODUCTION

This chapter contains detailed examples showing the application of the system described in chapter 4. The examples illustrate various aspects of the music recognition problem, including staveline-finding, segmentation, the processing of some handwritten fragments, dealing with a multi-stave system and the production of output in the form of M.R.L. data. Initially, printed (i.e. engraved) music extracts were used as source material, but the occasional use of handwritten material served to illustrate, and help enhance, the robust nature of the system. Also it was found to be convenient to write tailored extracts including the appropriate features required for testing the system at a particular stage of development. Such artificial material was to some extent constrained, however, so that the development of the system was not diverted into solving problems which normally only occur in handwritten music. The variations which commonly occur in engraved music due to poor print quality do to some extent correspond to those inherent in handwritten music. For example, variations in thickness and straightness of lines (stavelines, notestems, etc.), different shapes of solid noteheads and multiple beams which run together. The illustrations of original engraved and handwritten material are reproduced life-size, except where indicated, while the examples of run-length encoding and sectioning are suitably enlarged. All

scanning was done at a resolution of 300 d.p.i..

5.2 WORKED EXAMPLES

Figure 5.1 shows part of the first page of the flute part from the B minor sonata of J. S. Bach published by Peters Edition. The faint, fragmented arcs are pencil markings indicating slurs on the original. The music content of the image includes numerous beams which obscure portions of stavelines, small-sized notation for appoggiaturas and a cue, and several examples of closely-spaced symbols. Figure 5.2 shows the result of processing figure 5.1 in order to find staveline sections and then removing these from the original image. There are several points of interest in figure 5.2. Due to the clipping of the original image, the bottom staveline of the lowest stave was missing and hence the stave-finding routine was unable to find five roughly equi-spaced and concurrent filaments in order to identify the presence of this (part-) stave. Consequently, no staveline sections have been found in this part of the image. In the image as a whole, the stavelines were nearly all continuous, with only the occasional short break, for example in the middle staveline of the top stave after the crotchet rest. In any case, these have not affected staveline recognition. Most of the symbols have been successfully isolated, including the cue notation. The main exceptions occur where a sharp or natural sign is within close proximity of another symbol, commonly its associated note. Sometimes, this is due to the engraving, because no staveline exists between the two symbols. Otherwise, the short fragment which is present has formed a section with average thickness above the threshold set for

Flöte
[Violine]

SONATE I

Joh. Seb. Bach
(1685-1750)

Andante

Edition Peters Nr. 4461a
© Copyright 1939 by C. F. Peters

11816

Figure 5.1 The opening page of the B minor flute sonata of J. S. Bach - reproduced with permission of Peters Edition. (80% life-size).

Flöte
[Violine]

SONATE I

Joh. Seb. Bach
(1685-1750)

Andante

6

11

16

19

24

25

27

34

38

3 Comb.

Figure 5.2 An image of part of figure 5.1 processed to remove staveline sections.

staveline thickness, often because it has run into one of the cross-strokes of a sharp sign. The line-tracking has been misled by the slightly-sloping beam in the last bar of the lowest complete stave where it has followed the beam rather than the true staveline - this would in turn have affected the beamed group recognition routines. The distortion of isolated symbols as a result of staveline section removal can be seen to be minimal, not beyond the possible effects of noise in an original image. Through the use of a line-tracking rather than a global approach to staveline processing, symbols outside the bounds of the stave have been left untouched.

Figure 5.3 shows a page from the 'cello part for the 'Hamburg' flute sonata of C.P.E. Bach. This is the page from which the illustrations for chapter 4 were taken (although in that case scanning was done at 400 d.p.i.). Figure 5.4 shows the image with the staveline sections removed. This shows that clear symbol isolation has been achieved in the main but also illustrates typical cases of part of a particular symbol coinciding with a staveline, i.e. the top of the bass clef symbol. In several occurrences of this situation the section formed where the bass clef symbol merges with the top staveline has a sufficiently high average thickness to exceed the threshold for maximum staveline thickness, resulting in preservation of the connectivity of the symbol. In other cases this is not so and the bass clef symbol is fragmented. This is not too much of a problem for the recognition stage as models for both versions of this particular symbol can be stored and applied, in conjunction with a procedure for detecting and associating the requisite pair of dots.

84 *tasto* *tasto* *p*

93 *f*

102 *tasto*

111 *tasto* *p*

120 *f* *p* *pp* *tasto* *f*

129 *tasto* 3

140 1 1

149 *tasto* *tasto* *tasto*

157 *p* *f* *p* *ff*

B. Schott's Söhne in Mainz JN 747

Figure 5.3 A page from the 'cello part to the 'Hamburg' flute sonata of C. P. E. Bach. (80% life-size).

5

Figure 5.4 is a musical score consisting of nine staves of music. The key signature is one sharp (F#). The staves are numbered 94, 97, 103, 111, 120, 129, 140, 149, and 157. The music includes various dynamics such as *p*, *f*, *pp*, and *ff*, and tempo markings such as *tasto*. The notation includes eighth notes, quarter notes, and rests.

Figure 5.4 An image of figure 5.3 processed to remove staveline sections.

Figure 5.5 shows an extreme case of stavelines being obscured by beamed note groups, in this case demisemiquavers. It can be seen in figure 5.6 that the line-tracking procedure has succeeded in following the stavelines correctly even in the situation where a beam coincided over its entire length with a staveline. While previous examples have shown the staveline-finding strategy to be a successful one, this example is stretching the line-following approach to its limits. An alternative approach might use a filter (i.e. a global operation) for removal of short vertical runs of pixels, given that the threshold for this has already been set by the filaments found. This would have to be localised in some way, to avoid affecting slurs and other thin symbols, possibly by making use of the positional information available regarding filaments. Perhaps a combination of line-following and then a back-up check using a filter of the above type might be useful. Another possible technique (the one favoured for future inclusion in the system) would involve a 'clustering' approach, which, intuition suggests, resembles the technique used by the human vision system. Here, links would be made between filaments, and a clustering technique applied to group together filaments from a common stave, in the process isolating hairpins and other extraneous filaments. This would also provide a 'structure' which would assist the interpolation process in finding staveline sections which were not categorised as filaments. Alternatively, the sections with average thickness below the established threshold for staveline thickness could be included in the clustering process together with some form of weighting which, in their case, would be lower than that of filaments (the discussion of annealing in Byrd's thesis [Byrd 1984] is relevant here).

poco animato

The image shows a page of musical notation for an orchestra. At the top, the tempo is marked *poco animato*. The score is divided into four staves: Picc. I, Picc. II, Fl. I, and Fl. II. Each staff begins with a dynamic marking of *p cresc.* (piano, crescendo). The notation consists of rhythmic patterns of eighth and sixteenth notes. Below the first system, there are two more systems of notation, each with four staves. The first system of these two shows a continuation of the rhythmic patterns. The second system shows a change in dynamics, with markings of *fff* (fortissimo) and *sf* (sforzando) appearing in each of the four staves. The notation includes various musical symbols such as slurs, accents, and dynamic markings.

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Figure 5.5 A page of orchestral extracts from the symphonies of Shostakovich - reproduced with the permission of Fentone Music. (80% life-size).

poco animato

Picc. I *p*

Picc. II *p cresc.*

Fl. I *p cresc.*

Fl. II *p cresc.*

Figure 5.6 An image of the upper-most four-stave system from figure 5.5 processed to remove staveline sections.

After the symbols had been isolated by the staveline-finding procedure, recognition had to be achieved. Initially, as outlined in section 4.10 (RECOGNITION), a set of models using graph structures and dimensional parameters was constructed. An object in the image being processed could then be compared with the relevant models and, in a large percentage of cases, a match found.

The development of the technique for analysing beamed note groups described in section 4.11 (ANALYSIS OF BEAMED NOTE GROUPS) led to the modification of the above approach. Although the use of graph structure-based models and associated dimensional parameters was to be retained, the availability of a robust method for detecting approximately vertical lines gave this form of symbol component added importance. The following figures provide detailed illustrations of the application of the ideas of section 4.11.

Figure 5.7 shows a complex beamed note group which formed an individual object after isolation from the stavelines. The horizontally-orientated run-length encoding of the object was produced, and the resulting data supplied to the original routine for the production of the transformed LAG (as explained in section 4.11). The resulting sections for the object are shown in figure 5.8. The high aspect ratio sections have been removed, as notestems, to produce figure 5.9. This illustrates the need for several further operations in order to analyse a wide range of beamed note groups. It can be seen that the rightmost notestem has not been identified, due to the value of the aspect ratio

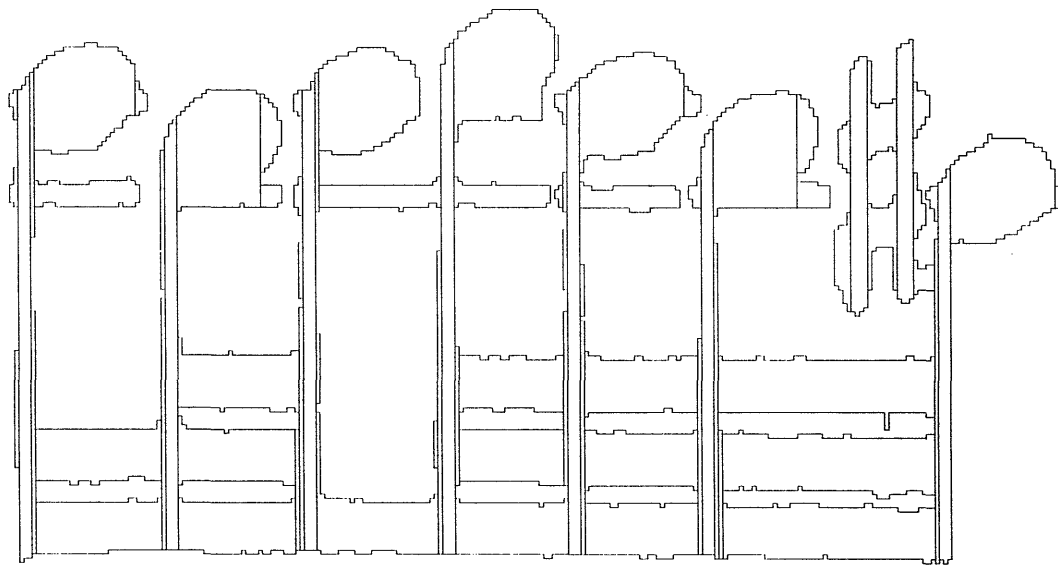


Figure 5.7 The constituent sections of a complex beamed group object isolated from the image shown in figure 5.2.

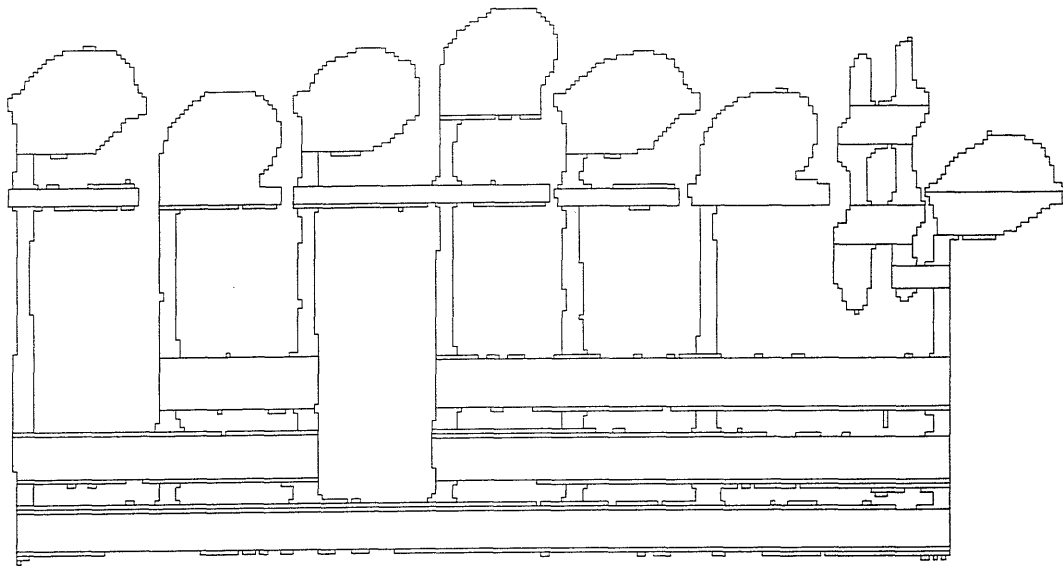


Figure 5.8 The object from figure 5.7 re-sectioned based on horizontally-orientated run-length encoding.

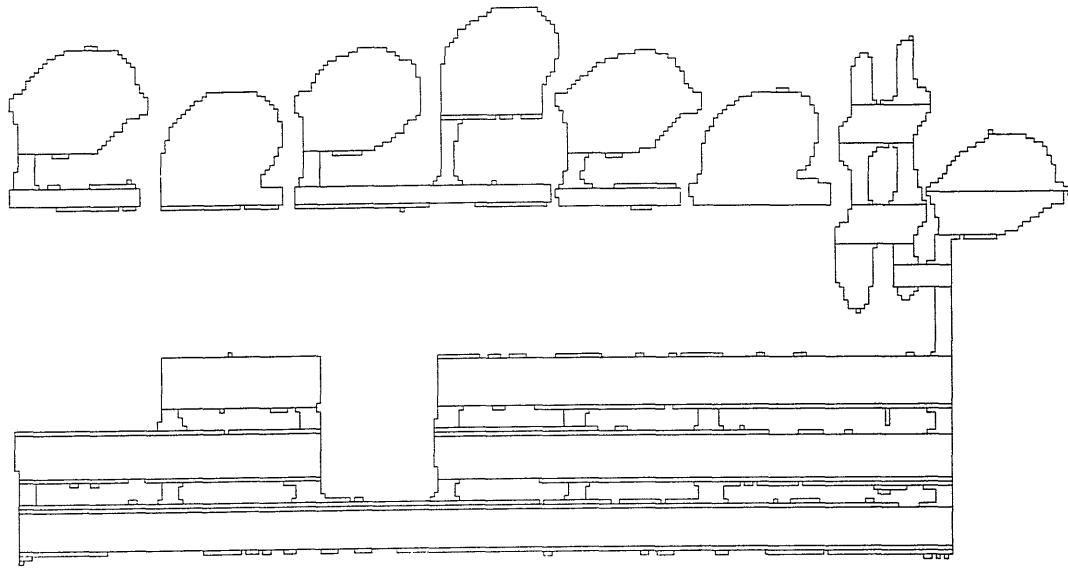


Figure 5.9 The sections shown in figure 5.8 processed to remove those of high aspect ratio.

threshold. In this example the effect is due to the attached sharp sign, but it may also be encountered where a short notestem occurs due to a particular combination of pitches or multiple beams. If the threshold was lowered, notestem fragments located either between a pair of ledger lines or between a ledger line and a notehead would also be extracted. This would necessitate the use of a collinearity test, in order to enable association of multiple notestem fragments with the appropriate note. It is proposed that this approach will be used in the future as part of beamed group analysis. The process required for counting ledger lines by examining a vertical strip extending downwards from the notehead has also been formalised but remains to be implemented and tested. This method for pitch determination will be robust despite the possible absence of various ledger line fragments (see, for example, the second, third and fourth notes in figure 5.9).

The principal problem which has emerged in applying the above method has involved breaks which occur in notestems. These cause noteheads to become separated and hence formed into separate objects rather than integrated with their associated beamed groups, as expected by the above procedure. This can be circumvented to a large extent by applying a vertically-orientated version of the low-pass filter described at the end of section 4.1. The existence of the problem depends on several factors, including the age of the printing plate, the thickness of the notestems in the original engraving and the print-quality of the sample being scanned. Usually notestems are thicker than stavelines and so the former are less likely to break up in the printing process. The example given in figure 5.10 illustrates the



Figure 5.10 The first three bars of the Allegro from the C major flute sonata of J. S. Bach - reproduced with permission of Boosey and Hawkes.



Figure 5.11 A reconstruction, using the SCORE desktop music publishing package, of the extract shown in figure 5.10. (80% of default size).

treatment of beamed groups using the above techniques whilst incorporating the problem of fragmented stems. Before it is discussed, the SCORE desktop music publishing package will be introduced, as it is used in figure 5.11, and the following figures, for reconstruction of the musical material.

A brief overview of the SCORE desktop music publishing package appeared in the Appendix to chapter 2. To amplify, it is a package for the IBM PC based on the work of Professor Leland Smith at Stanford University. It uses QWERTY keyboard, mouse or non-real-time MIDI keyboard for input, its own unique internal representational system and produces output on dot-matrix or Postscript printers including compatible phototypesetters. An important facility allows a file containing M.R.L. data to be prepared externally, using a wordprocessor or, in this case, by the recognition software, and then imported into SCORE. The M.R.L. uses a letter and octave number to represent pitch and either numbers (4 = crotchet, 8 = quaver, etc.) or, in some cases, letters to represent rhythm. Beaming information, slur positions and miscellaneous markings (including text underlay) are all entered separately. The vocabulary of symbols is extensive and, in addition, there is a facility which enables the integration of user-defined symbols.

To return to figure 5.10, this shows an extract from the Allegro from J.S.Bach's C major flute sonata. The reconstruction of the musical material achieved using the SCORE package and printed using a 300 d.p.i. Postscript laser printer is shown in figure 5.11. Initially, 10 of the noteheads were separated from

their respective beamed note groups due to breaks in the notestems (although this may not be the case in the illustration seen here, due to the reproduction process). The vertically-orientated low-pass filtering operation described above removed all but one of these breaks; the one remaining break caused the misrecognition of the second note in the eighth group. Only beamed groups were processed at this stage in order to thoroughly test the new method for their analysis - the other symbols present in the reconstruction were added by default.

In order to encompass fragmented stems with breaks larger than those filled by filtering, the beamed group recognition software would have to include a procedure for associating objects. Where a fragment of notestem existed which was large enough to be identified as such by the vertical line-finding procedure of the beamed group analysis routine, the original image could be searched in the relevant region for the notehead. In the much rarer case, where the stem is broken into several fragments, a more complicated procedure for assemblage would have to be undertaken. This processing option would have to be generally available eventually so that other grossly fragmented symbols could be recombined into meaningful structures. A clustering technique along the lines of the one suggested as a possible approach to staveline fragment association may be suitable. Coping with an image of the poor quality now being discussed would be a tremendous challenge, especially considering that text of such quality would almost certainly defeat existing OCR systems.

Another factor, briefly touched on in section 4.10 is the

relatively common occurrence of overlapping or superimposed symbols. These need to be separated out by a specific algorithm and it is proposed to start by extracting lines, in any orientation, from such a compound symbol. This would remove barlines, slurs and hairpins - the most commonly intersecting symbols. Similarly, in situations where one symbol becomes inadvertently attached to another (e.g. the sharp signs attached to noteheads in figure 5.2), an approach based on iterative removal of elementary symbols and symbol components is advocated. Thus, by first identifying and removing the notestem and notehead of an individual note, the appended sharp (or similar) sign could then be recognised in isolation.

Figures 5.12 to 5.16 show the stages involved in processing a short handwritten extract. The original image is shown in figure 5.12, while the same image with its staveline sections removed is shown in figure 5.13. A fragment of the original image with sections illustrated is shown in figure 5.14. The SCORE M.R.L. data file produced as a result of processing the extract is shown in figure 5.15. The sectioning illustrates the earlier comment that the characteristics of the handwritten extracts used were intended to test the recognition system but not to force extension of its scope to include all handwritten notation. For instance, the variable thickness and straightness of the notestems was a reasonable test which was satisfactorily negotiated by the techniques outlined above, while the shapes of the noteheads were kept reasonably close to those found in engraved notation, something which does not apply widely to handwritten manuscripts. The reconstruction of the extract, obtained using the data file of



Figure 5.12 A short handwritten extract.



Figure 5.13 The image of figure 5.12 processed to remove staveline sections.

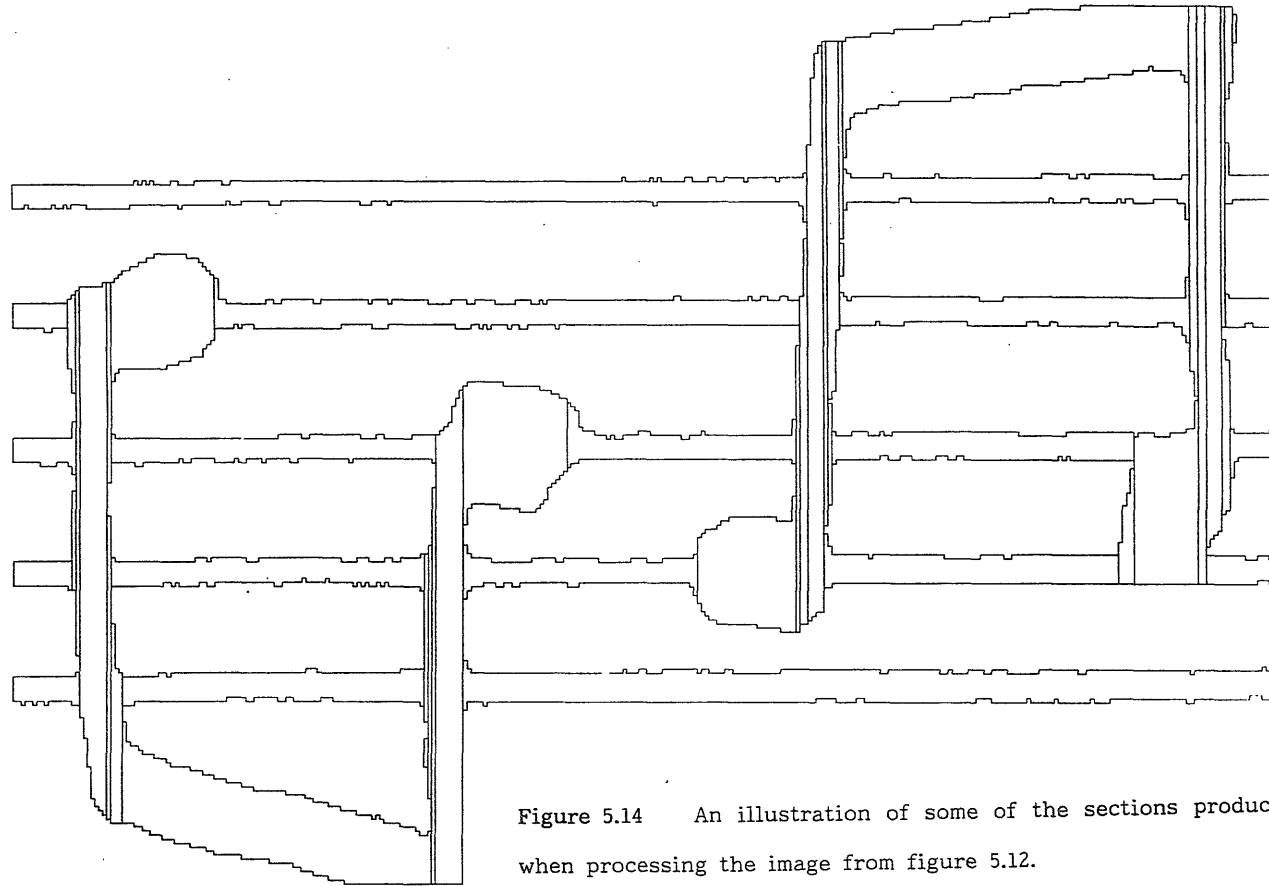


Figure 5.14 An illustration of some of the sections produced when processing the image from figure 5.12.

figure 5.15, is shown in figure 5.16. This was printed in the same way as figure 5.11.

Figure 5.17 shows a more complex handwritten extract containing a three-stave system. This was used in testing both the beamed group analysis routine and also the ability of the system to cope with objects (the barlines) which were associated with multiple staves. The ordering of the staves, as well as symbols within individual staves, in order to produce the correct SCORE M.R.L. data file, had also to be achieved. The processed version of figure 5.17, with staveline sections removed, is shown in figure 5.18. The problem regarding a part of a symbol coinciding completely with a staveline is illustrated here in each of the three clefs. As stated earlier in this chapter, the bass clef could be recognised regardless of fragmentation, by making available alternative models, while in the cases of the other clefs the bounding rectangle was not affected and this was used in conjunction with positional information to achieve recognition. A rudimentary object association routine (see above regarding assembling fragmented symbols) was used to 'connect' the bass clef components, including the pair of dots. All the other objects were analysed using the techniques described in section 4.11. The barlines were recognised as objects which contained a single vertical line which constituted over 90% of the total area of the object - this allowed for any remaining extraneous noise sections. A list of associated staves was established for each object, containing three entries in the case of each barline and one for each of the other objects. The stave numbers of the staveline sections had previously been sorted so that the staves were



Figure 5.17 A short, handwritten trio extract (three-stave system).

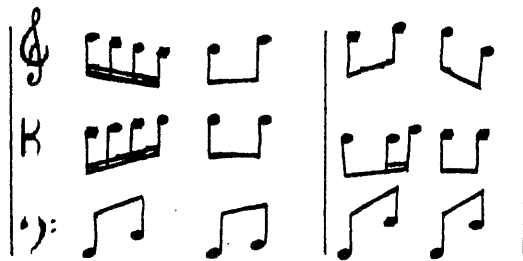


Figure 5.18 The image of figure 5.17 processed to remove staveline sections.

numbered in ascending order from one, which was the lowest on the page. This corresponded to the organisation used by SCORE. The SCORE M.R.L. data file resulting from processing figure 5.17 is shown in figure 5.19. The three blocks of data corresponding to the three staves can be seen, while the code 'M3' indicates a barline stretching over three staves. The reconstruction of the extract, produced using the data of figure 5.19 appears in figure 5.20.

```

IN 1
0
M3/BA/G2/D3/G2/B2/M3/G2/G3/G2/F3/M3;
8/8/8/8/8/8/8/8;
;
1 2/3 4/5 6/7 8;
;
IN 2
SP 1
AL/D4/E4/F4/G4/G4/C4/C4/E4/D4/D4;
16/16/16/16/8/8/8/16/16/8/8;
;
1 4/5 6/7 9/10 11;
;
IN 3
SP 1
TR/D5/C5/B4/A4/B4/D5/E5/G5/F5/B4;
16/16/16/16/8/8/8/8/8/8;
;
1 4/5 6/7 8/9 10;
;

```

Figure 5.19 The SCORE data file resulting from processing the image of figure 5.17.



Figure 5.20 The SCORE reconstruction of figure 5.17 using the data shown in figure 5.19. (80% of default size).

6. Conclusions

The main strength of the system described in chapters 4 and 5, as with other structural pattern recognition systems, lies in its flexibility. The system is, in effect, omnifont and size-independent and its significant tolerance of noise, limited rotation, broken print and distortion is a major asset. The manipulation of areas of black pixels (sections), as entities in themselves, enables fast processing. The only pixel level operations are carried out in the first pass over the data and even these could be undertaken using hardware already incorporated in an appropriate scanner. In addition, parallel processing techniques could be employed, by breaking up the image and allocating each portion to its own processor for concurrent production of run-length encoding, formation of transformed LAG, or both. All routines are implemented in 'C' under the UNIX operating system and run on both a Gould minicomputer and a Hewlett Packard 300 series desktop workstation, illustrating their portability.

Further comment needs to be made with regard to run-times and memory requirements. Any form of processing of full A4-page images at 300 d.p.i., even binary images stored using bit-per-pixel representation, requires significant amounts of memory. Unfortunately, neither of the above machines provided more than 1 1/2 to 2 Mbytes of user workspace. Given that a single image may require approximately 1 Mbyte and storage of data structures for representing sections and objects could increase this requirement

to between six and 10 Mbytes, it can be appreciated that problems were encountered due to page faults when processing large images. In the case of the extract shown in figure 4.10, however, total processing time was approximately 30s, from reading the image from disk to producing the text interpretation file.

The processing of the image of figure 5.17 through to producing the SCORE M.R.L. data file shown in figure 5.19 took approximately 45s. The increase in processing time is roughly in proportion to the area of the score image involved, given the limitations of the development environment mentioned above for testing this. The production of run-length encoding and section data requires a significant proportion of the total processing time, but obviously the run-time of procedures such as stave finding depend on the musical content of the particular image involved.

The structural approach, by its nature, allows for both 'character' and 'varying graphical parameter' types of symbol. As with Prerau's efforts, an easily expandable program was the aim and has in the most part been achieved. The overall structure of the software was kept modular so that separate routines could be modified, replaced, optimized or expanded. The system is a real one in Mahoney's terms, in that it tackles 'real world' problems but still needs expanding to cope with a wider range of symbols and score formats. As mentioned in section 3.3.2, a trade-off exists between robustness and simplicity of the recognition task. Processing stavelines is a prime example. If assumptions are made that the lines are horizontal or perhaps, as Roach and Tatem

specified, exist across a large proportion of the width of the page, then their detection becomes far easier. In 'real world' situations, however, as Prerau noted, the lines cannot be assumed to be exactly parallel, horizontal, equidistant, of constant thickness or straight. Also, stavelines may be obscured to a significant extent by multiple beams, particularly where these are horizontal. All the above factors combine, in the general case, to invalidate the use of standard image processing techniques for locating stavelines, a fact corroborated by Roach and Tatem. The system was developed with these facts in mind.

As outlined in sections 4.10 and 4.11, the current methods could be extended to include all symbols which contain vertically-orientated linear components, i.e. individual notes with stems, all beamed groups, barlines, quaver (and shorter duration) rests, sharp, natural, flat and double flat signs, boxes (surrounding bar numbers or text) and brackets. Also included would be those symbols which can be modelled using a graph structure-based representation of the simplified original transformed LAG, in conjunction with the appropriate parameters for describing the dimensions and spatial organisation of the constituent sections. These two techniques operating in conjunction should cover the majority of conventional music symbols. It is anticipated that difficulties will be encountered where, for example, grace notes or other small symbols cannot be consistently analysed by structural breakdown due to the limits on print quality and scanning resolution.

Some areas have been identified which may prove problematical

in the context of future work, and possible solutions or approaches have been suggested. The difficulties resulting from fragmentation of symbols due to poor print quality have been circumvented to a significant extent by the techniques presented in chapters four and five. Severe break-up of symbols will, however, continue to be a problem for a topology-based approach and will probably necessitate the use of artificial intelligence-based techniques in order to take advantage of higher level musical information. Similarly, suggestions have been made regarding the processing of overlapping symbols, but with the large number of possible combinations of symbols which are permitted to intersect, it would be unrealistic to expect any single method to cope with all situations. A method based on isolating characteristic sections within a composite object, and using these as the basis of an iterative process for separating out the merged symbols, has been proposed as a limited solution.

The main areas of concern pertaining to more widespread use of existing techniques have been mentioned in chapter five. These are :- symbols which remain attached after staveline removal, removal of symbol components by the staveline identification process and residual staveline fragments. The first of these can, perhaps, be categorised with the question of overlapping symbols as it may be a product of the original engraving rather than the result of the staveline identification technique. Otherwise, the problems all seem related to the initial symbol isolation, for if this is not perfect, there will always be a need for compromise methods which compensate for the weaknesses of the staveline-finding technique. As discussed in chapter five, the present approach to staveline-finding may, in the future, be

supplemented by a clustering-based technique. This should give better symbol isolation and hence further simplify the recognition task.

From the start of the research, it was acknowledged that the text present in music images would be treated separately. After isolation, recognition of the text could be achieved either using existing techniques, possibly modified to use a dictionary (in processing Italian terms and the like), or by making use of a new method aimed at identifying not just the text but also its font. It was hoped that the segmentation techniques developed for processing the music symbols could be applied to some degree when dealing with text and this may prove possible in the case of the orthogonal LAGs.

The intention was to place no restriction on the symbols which could eventually be included. Similarly, due to the way processing was carried out, no limit was placed on the formats which could be read. Chords and multiple voices on a single staff have not been excluded by the approach which has been taken and it is hoped that more complex music including these features will be fully encompassed as part of future research. Originally, a target

processing time of five to 10 minutes was set for a complete A4 page of music of 'average' complexity and the results so far achieved indicate that this will be met. The use of run length encoding as the basis of the segmentation process also satisfies a desire for data compression and consequently opens up the possibility of using a scanner with this facility built in to its hardware (usually this is in connection with Group III/IV facsimile transmission), as mentioned in section 4.3.

The fixing of the line thickness threshold used in staveline-pixel allocation before commencement of processing is a weakness of several of the systems described in section 3.3. The author's system avoids this by setting up the line thickness threshold based on the thickness of all the filaments found in the image. Importantly, the threshold is applied to complete sections as an *average* thickness measure. Filaments themselves are located using a purely relative measure, namely aspect ratio.

Postscript

Bearing in mind the subject field, the reader may be interested to have details regarding the production of this thesis. The text was prepared using 'Chiwriter' a 'scientific' word-processing package running on an IBM PC-compatible running Sun Microsystems PC-NFS (Network File System) over an Ethernet network in conjunction with the Physics department Gould minicomputer. Some use was also made of the vi text editor running on the latter machine, under BSD 4.2 Unix - this was the main development environment for the automatic recognition system, as mentioned in chapter 6. The SCORE desktop music publishing package was used to produce the music examples in chapter 2 and, where stated, in chapter 5. Text output and illustrations other than SCORE output (and reproductions of published music) were produced on an Epson GQ-3500, 300 d.p.i. laser printer, whilst the SCORE examples were printed on a QMS PS-810 Postscript laser printer.

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